

HOMEWORK #6 SOLUTIONS

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1. OVSM

5.14.4 (Sam Gansfried) Define $f : NVB[a, b] \rightarrow \mathbb{R}$ with $f(v) = v((a+b)/2)$. This is clearly linear, and

$$\|f(v)\| \leq TV(v)$$

so it is bounded. If $C[a, b]$ were reflexive we could find x such that $\int_a^b x(t)dv(t) = v((a+b)/2)$ for all v . However, if we let v_α be a step function which is 0 before α and 1 after, we get the integral to be $x(\alpha)$. If $\alpha < (a+b)/2$ we have $v_\alpha((a+b)/2) = 1$, otherwise we have $v_\alpha((a+b)/2) = 0$, so we have that x is a step function that goes from 1 to 0 at $(a+b)/2$. But if we now let

$$v(t) = \left(t - \frac{3a+b}{4}\right)^2 - \frac{(b-a)^2}{16}$$

we get $\int_a^b x(t)dv(t)$ is the variation of v on $[a, (a+b)/2]$ (which is nonzero) while $v((a+b)/2) = 0$. So there is no such $x \in C[a, b]$ and therefore $C[a, b]$ is not reflexive.

5.14.6 We know that $d^2x/dt^2 = u(t)$, so integrating this twice we get the following equations:

$$\frac{dx}{dt}(T) = 1 + \int_0^T u(t) dt \quad x(T) = x(0) + T + \int_0^T \int_0^t u(s) ds dt.$$

Switching the order of integration in the second integral and expanding we get that

$$x(T) = T \frac{dx}{dt}(T) - \int_0^T tu(t) dt.$$

In the optimal solution for x we will stop once we reach the origin, so $\frac{dx}{dt}(T) = 0$. Thus we now have the following three conditions:

$$x(T) = - \int_0^T tu(t) dt \quad \int_0^T tu(t) dt = 0 \quad |u(t)| \leq 1.$$

For any fixed time T , let S_T be the set of functions u that satisfy the first two of these conditions. We want to find the minimum T' such that $S_{T'}$ contains a function u with $\max_t |u(t)| \leq 1$. Thus we want to minimize T such that

$$\min_{u \in S_T} \max_t |u(t)| = 1.$$

Notice that the function $\min_{S_T} \max_t |u(t)|$ shrinks as a function of T ; thus if we find some T such that the above holds, we will have found the global minimum.

However, we can reduce this to a problem in L_1 : we want to find the u in S_T such that $\langle 1, u \rangle = -1$ and $\langle t, u \rangle = 0$. But we know that then in L_∞ ,

$$\min_T \|u\|_\infty = \max_{\|a_1 + a_2 t\|_1 \leq 1} -a_1$$

with the optimal u aligned with the optimal $a_1 + a_2 t$. Two functions in L_∞ and L_1 will be aligned if and only if $y(t) = \text{rsgn}(x(t))$ for $r \in \mathbb{R}$. Thus we want a solution where we decelerate as fast as possible, and then break at the last minute.

Knowing this, we can solve the two constraints that we have to find that $T = 1 + \sqrt{2}$.
 5.14.10 First we will show that $M^* = X^*/M^\perp$. Consider a map in M^* , m^* . By Hahn-Banach there exists a map \tilde{m}^* such that $\tilde{m}^*|_M = m^*$ and such that $\|\tilde{m}^*\| = \|m^*\|$. This map is well-defined on X^*/M^\perp , since if x^* is another such extension then $\tilde{m}^* - x^*$ is zero on M , and therefore in M^\perp . It is also clearly linear. If we define $f : M^* \rightarrow X^*/M^\perp$ by $m^* \mapsto \tilde{m}^*$, we claim that we have an isometric isomorphism.

Indeed, suppose that $\tilde{m}^* = \tilde{n}^*$. Then, on M , $\tilde{m}^* - \tilde{n}^* = 0$, which means that $m^* = n^*$, so the map is injective. Now consider $[x^*] \in X^*/M^\perp$. Then the functional $\tilde{x^*}|_M$ will be the same on M as x^* , and so will be in $[x^*]$. Thus the map is surjective. So it only remains to show that it is an isometry. Notice that for any $x^* \in M^\perp$,

$$\|\tilde{m}^* + x^*\| = \sup_{\|x\|=1} |(\tilde{m}^* + x^*)(x)| \geq \sup_{\substack{\|x\|=1 \\ x \in M}} |(\tilde{m}^* + x^*)(x)| = \|m^*\|_M = \|\tilde{m}^*\|.$$

Therefore, $\inf_{x^* \in M^\perp} \|\tilde{m}^* + x^*\| = \|m^*\|$, so the map is an isometry.

Now we will show that $M^\perp = (X/M)^*$. We will show that the map defined by $f(x^*)([y]) = x^*(y)$ is the isometric isomorphism we want. The map is clearly linear. It is well-defined because each x^* is 0 on M , so adding an element of M to y would not change the map. The map is injective because if $f(x^*) = 0$ then $x^* = 0$ on all elements of X , so $x^* = 0$. Consider a map $y^* \in (X/M)^*$. We can define x^* by $x^*(x) = y^*(x)$. This will be in M^\perp since $[m] = [0]$ for all $m \in M$, and $f(x^*) = y^*$. So the map is surjective. Also,

$$\|f(x^*)\| = \sup_{\|[x]\|=1} |f(x^*)(x)| = \sup_{\|x\|=1} |x^*(x)| = \|x^*\|$$

so the map is an isometry.

5.14.11 We define $x^*(x) = \lim_{k \rightarrow \infty} x_k^*(x)$. We need to show that the right-hand side converges and that the left-hand side will be a linear functional. (It would clearly be bounded since the sequence of x_k^* 's is bounded.)

Let D be the dense set on which the x_k converge, and let M be the bound on $\{x_k^*\}$. Fix a point $x \in X$. We know that for any $\epsilon > 0$ there exists a point $y \in D$ such that $\|x - y\| < \epsilon/3M$. We know that there exists an N such that $|\langle y, x_n^* \rangle - \langle y, x_m^* \rangle| < \epsilon/3$ for all $m, n > N$. (Note that x^* is well-defined on D .) Then we know that

$$\begin{aligned} |\langle x, x_n^* \rangle - \langle x, x_m^* \rangle| &\leq |\langle x, x_n^* \rangle - \langle y, x_n^* \rangle| + |\langle y, x_n^* \rangle - \langle y, x_m^* \rangle| + |\langle y, x_m^* \rangle - \langle x, x_m^* \rangle| \\ &\leq \|x - y\| \cdot \|x_n^*\| + \epsilon/3 + \|y - x\| \cdot \|x_m^*\| \\ &< \epsilon. \end{aligned}$$

Thus we know that $\{\langle x, x_n^* \rangle\}$ is a Cauchy sequence in \mathbb{R} , so it converges, so x^* converges on all of X . Now we just need to show that it is linear. However, notice

that

$$x^*(\alpha x + y) = \lim_{k \rightarrow \infty} (x_k^*(\alpha x + y)) = \lim_{k \rightarrow \infty} (\alpha x_k^*(x) + x_k^*(y)) = \alpha \lim_{k \rightarrow \infty} x_k^*(x) + \lim_{k \rightarrow \infty} x_k^*(y) = \alpha x^*(x) + x^*(y),$$

as desired. Notice that we can expand the limit because we know that each of the separate parts of the sum converges pointwise. Thus the sequence $\{x_k^*\}$ converges weak* to x^* .

5.14.15 Consider the linear map $F : X \rightarrow \mathbb{R}^n$ defined by $x \mapsto (f_1(x), \dots, f_n(x))$. Let $\alpha = (\alpha_1, \dots, \alpha_n)$. We want to show that α is in the image of F if and only if for all $\lambda_1, \dots, \lambda_n$, if $\sum \lambda_i f_i = 0$, then $\sum \lambda_i \alpha_i = 0$.

The forward direction is easy. If there exists x such that $F(x) = \alpha$, then $\sum \lambda_i f_i = 0$ implies that $\sum \lambda_i f_i(x) = \sum \lambda_i \alpha_i = 0$.

Now suppose that we know that if $\sum \lambda_i f_i = 0$ then $\sum \lambda_i \alpha_i = 0$. We will show that α is in the image of F . Let v_1, \dots, v_n be an orthonormal basis for \mathbb{R}^n such that v_1, \dots, v_m is an orthonormal basis for the image of F . If $\alpha = 0$ then clearly it is in the image of F and we are done. If $m = n$ we are done, since the image of F is the entire space. If $m < n$ we can define the functional $v_j : \mathbb{R}^n \rightarrow \mathbb{R}$ by $\sum a_i v_i \mapsto a_j$, for $j > m$. If we now take \tilde{v}_j , the same functional defined in terms of the standard basis on \mathbb{R}^n , we will have a functional \tilde{v}_j which is zero on the image of F . Then we know that $\tilde{v}_j \alpha = 0$, so the j -th coordinate of α in the v -basis was 0. However, this is the case for all $j > m$, so α is in the image of F and we are done.

5.14.16 Let $N_i = \ker g_i$. Each of these has codimension 1 since each g is a functional. Let $N = \bigcap_{i=1}^n N_i$, the joint kernel of all of the g 's. This has codimension at most n , so we know that X/N is a finite-dimensional vector space. Each of the g_i is well-defined on X/N since $N \subset N_i$ for all i . The given conditions also imply that f is well-defined on X/N . So now we just need to show the desired statement for X/N , which is a finite-dimensional vector space of dimension at most n .

For each $g_i \in (X/N)^*$ there exists a $y_i \in X/N$ such that $g_i(x) = \langle x, y_i \rangle$ for all x . There also exists such a y for x . Thus showing that f is in the span of the g_i is equivalent to showing that y is in the span of the y_i . However, we know that $\dim(X/N)^* = \dim(X/N) \leq n$ and we have $n + 1$ vectors, so there are constants a_1, \dots, a_n, a such that

$$\sum_{i=1}^n a_i y_i + a y = 0.$$

However, since the g_i are linearly independent, the y_i are linearly independent and so $a \neq 0$. Therefore, if we let $\lambda_i = -a_i/a$ we have the desired result.