

example: Let V be a ^{finite-dim.} vector space over \mathbb{C} . (3)

Then $T: V \rightarrow V$ is diagonalizable if and only if all the Jordan blocks in the Jordan canonical form for T are 1×1 matrices.

The Jordan canonical form theorem

~~theorem~~, which is contained in Chapter 7

of the textbook, gives a complete answer

to one of our major questions from the

beginning of the course: "given

$T: V \rightarrow V$ a linear map, if I am

allowed to choose a basis β for V then

how simple can I make the matrix

$[T]_{\beta}^{\beta}$ look?"

It will also allow us to fill in the missing

part of our work on linear differential

equations: if the auxiliary polynomial