

TAKING A TO BE DIFFERENT MATRICES YIELDS

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

ABOUT Y-AXIS

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

ABOUT X-AXIS

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

ABOUT Y=X

REFLECTIONS

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

ABOUT XY PLANE

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ABOUT XZ PLANE

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ABOUT YZ PLANE

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

ONTO X-AXIS

$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

ONTO Y-AXIS

ORTHOGONAL PROJECTIONS

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

ONTO XY PLANE

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ONTO XZ PLANE

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ONTO YZ PLANE

$$\begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

ABOUT ORIGIN

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{bmatrix}$$

ABOUT POSITIVE X-AXIS

COUNTER-CLOCKWISE ROTATIONS

$$\begin{bmatrix} \cos\theta & 0 & \sin\theta \\ 0 & 1 & 0 \\ -\sin\theta & 0 & \cos\theta \end{bmatrix}$$

ABOUT POSITIVE Y-AXIS

$$\begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ABOUT POSITIVE Z-AXIS

$$\begin{bmatrix} k & 0 \\ 0 & k \end{bmatrix}$$

$$\begin{bmatrix} k & 0 & 0 \\ 0 & k & 0 \\ 0 & 0 & k \end{bmatrix}$$

CONTRACTIONS WHEN $0 \leq k \leq 1$
DILATIONS WHEN $k \geq 1$

THE STANDARD MATRIX FOR $T_B \circ T_A(\vec{x})$ IS BA .

THE STANDARD MATRIX FOR $T_C \circ T_B \circ T_A(\vec{x})$ IS CBA .