

## Section 5.2

8.  $A = \begin{bmatrix} 7 & -2 \\ 2 & 3 \end{bmatrix}$ ,  $A - \lambda I = \begin{bmatrix} 7 - \lambda & -2 \\ 2 & 3 - \lambda \end{bmatrix}$ . The characteristic polynomial is

$$\det(A - \lambda I) = (7 - \lambda)(3 - \lambda) - (-2)(2) = \lambda^2 - 10\lambda + 25$$

Since  $\lambda^2 - 10\lambda + 25 = (\lambda - 5)^2$ , the only eigenvalue is 5, with multiplicity 2.

10.  $\det(A - \lambda I) = \det \begin{bmatrix} 0 - \lambda & 3 & 1 \\ 3 & 0 - \lambda & 2 \\ 1 & 2 & 0 - \lambda \end{bmatrix}$ . From the special formula for  $3 \times 3$  determinants, the

characteristic polynomial is

$$\begin{aligned} \det(A - \lambda I) &= (-\lambda)(-\lambda)(-\lambda) + 3 \cdot 2 \cdot 1 + 1 \cdot 3 \cdot 2 - 1 \cdot (-\lambda) \cdot 1 - 2 \cdot 2 \cdot (-\lambda) - (-\lambda) \cdot 3 \cdot 3 \\ &= -\lambda^3 + 6 + 6 + \lambda + 4\lambda + 9\lambda = -\lambda^3 + 14\lambda + 12 \end{aligned}$$

16. The determinant of a triangular matrix is the product of its diagonal entries:

$$\det(A - \lambda I) = \det \begin{bmatrix} 5 - \lambda & 0 & 0 & 0 \\ 8 & -4 - \lambda & 0 & 0 \\ 0 & 7 & 1 - \lambda & 0 \\ 1 & -5 & 2 & 1 - \lambda \end{bmatrix} = (5 - \lambda)(-4 - \lambda)(1 - \lambda)^2$$

The eigenvalues are 5, 1, 1, and  $-4$ .

20.  $\det(A^T - \lambda I) = \det(A^T - \lambda I^T)$   
 $= \det(A - \lambda I)^T$  Transpose property  
 $= \det(A - \lambda I)$  Theorem 3(c)

24. First, observe that if  $P$  is invertible, then Theorem 3(b) shows that

$$1 = \det I = \det(PP^{-1}) = (\det P)(\det P^{-1})$$

Use Theorem 3(b) again when  $A = PBP^{-1}$ ,

$$\det A = \det(PBP^{-1}) = (\det P)(\det B)(\det P^{-1}) = (\det B)(\det P)(\det P^{-1}) = \det B$$

26. If  $a \neq 0$ , then  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \sim \begin{bmatrix} a & b \\ 0 & d - ca^{-1}b \end{bmatrix} = U$ , and  $\det A = (a)(d - ca^{-1}b) = ad - bc$ . If  $a = 0$ , then

$$A = \begin{bmatrix} 0 & b \\ c & d \end{bmatrix} \sim \begin{bmatrix} c & d \\ 0 & b \end{bmatrix} = U \text{ (with one interchange), so } \det A = (-1)^1(cb) = 0 - bc = ad - bc.$$

## Section 5.3

2.  $P = \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix}$ ,  $D = \begin{bmatrix} 1 & 0 \\ 0 & 1/2 \end{bmatrix}$ ,  $A = PDP^{-1}$ , and  $A^4 = PD^4P^{-1}$ . We compute

$$P^{-1} = \begin{bmatrix} 5 & 3 \\ 3 & 2 \end{bmatrix}, D^4 = \begin{bmatrix} 1 & 0 \\ 0 & 1/16 \end{bmatrix}, \text{ and } A^4 = \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1/16 \end{bmatrix} \begin{bmatrix} 5 & 3 \\ 3 & 2 \end{bmatrix} = \frac{1}{16} \begin{bmatrix} 151 & 90 \\ -225 & -134 \end{bmatrix}$$

$$4. A^k = PD^kP^{-1} = \begin{bmatrix} 3 & 4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2^k & 0 \\ 0 & 1^k \end{bmatrix} \begin{bmatrix} -1 & 4 \\ 1 & -3 \end{bmatrix} = \begin{bmatrix} 4-3 \cdot 2^k & 12 \cdot 2^k - 12 \\ 1-2^k & 4 \cdot 2^k - 3 \end{bmatrix}.$$

6. As in Exercise 5, inspection of the factorization gives:

$$\lambda = 4: \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}; \lambda = 5: \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

14. The eigenvalues of  $A$  are given to be 5 and 4.

For  $\lambda = 5$ :  $A - 5I = \begin{bmatrix} -1 & 0 & -2 \\ 2 & 0 & 4 \\ 0 & 0 & 0 \end{bmatrix}$ , and row reducing  $[A - 5I \quad \mathbf{0}]$  yields  $\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ . The general

solution is  $x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$ , and a basis for the eigenspace is  $\{\mathbf{v}_1, \mathbf{v}_2\} = \left\{ \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ .

For  $\lambda = 4$ :  $A - 4I = \begin{bmatrix} 0 & 0 & -2 \\ 2 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix}$ , and row reducing  $[A - 4I \quad \mathbf{0}]$  yields  $\begin{bmatrix} 1 & 1/2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ . The general

solution is  $x_3 \begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix}$ , and a nice basis vector for the eigenspace is  $\mathbf{v}_3 = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}$ .

From  $\mathbf{v}_1, \mathbf{v}_2$  and  $\mathbf{v}_3$ , construct  $P = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \mathbf{v}_3] = \begin{bmatrix} -2 & 0 & -1 \\ 0 & 1 & 2 \\ 1 & 0 & 0 \end{bmatrix}$ . Then set  $D = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 4 \end{bmatrix}$ , where the

eigenvalues in  $D$  correspond to  $\mathbf{v}_1, \mathbf{v}_2$  and  $\mathbf{v}_3$  respectively.

20. Since  $A$  is triangular, its eigenvalues are obviously 4 and 2.

For  $\lambda = 4$ :  $A - 4I = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 1 & 0 & 0 & -2 \end{bmatrix}$ , and row reducing  $[A - 4I \ \mathbf{0}]$  yields  $\begin{bmatrix} 1 & 0 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ . The

general solution is  $x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 0 \\ 0 \\ 1 \end{bmatrix}$ , and a basis for the eigenspace is  $\{\mathbf{v}_1, \mathbf{v}_2\} = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ .

For  $\lambda = 2$ :  $A - 2I = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$ , and row reducing  $[A - 2I \ \mathbf{0}]$  yields  $\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ . The

general solution is  $x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$ , and a basis for the eigenspace is  $\{\mathbf{v}_3, \mathbf{v}_4\} = \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ .

From  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  and  $\mathbf{v}_4$  construct  $P = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3 \ \mathbf{v}_4] = \begin{bmatrix} 0 & 2 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ . Then set  $D = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$ ,

where the eigenvalues in  $D$  correspond to  $\mathbf{v}_1, \mathbf{v}_2$  and  $\mathbf{v}_3$  respectively.

26. Yes, if the third eigenspace is only one-dimensional. In this case, the sum of the dimensions of the eigenspaces will be six, whereas the matrix is  $7 \times 7$ . See Theorem 7(b). An argument similar to that for Exercise 24 can also be given.

28. If  $A$  has  $n$  linearly independent eigenvectors, then by the Diagonalization Theorem,  $A = PDP^{-1}$  for some invertible  $P$  and diagonal  $D$ . Using properties of transposes,

$$\begin{aligned} A^T &= (PDP^{-1})^T = (P^{-1})^T D^T P^T \\ &= (P^T)^{-1} D P^T = QDQ^{-1} \end{aligned}$$

where  $Q = (P^T)^{-1}$ . Thus  $A^T$  is diagonalizable. By the Diagonalization Theorem, the columns of  $Q$  are  $n$  linearly independent eigenvectors of  $A^T$ .

30. A nonzero multiple of an eigenvector is another eigenvector. To produce  $P_2$ , simply multiply one or both columns of  $P$  by a nonzero scalar unequal to 1.