

A surface integral is

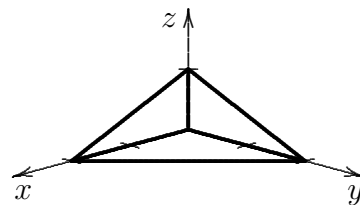
$$\iint_S f(x, y, z) \, dS = \iint_D f(\mathbf{r}(u, v)) \, |\mathbf{r}_u \times \mathbf{r}_v| \, du \, dv,$$

where f is a function defined on the parametric surface $\mathbf{r}(u, v)$.

1 Evaluate the surface integral

$$\iint_S (1 + z) \, dS,$$

where S is that part of the plane $x + y + 2z = 2$ in the first octant.



Suppose $\mathbf{F}$ is a continuous vector field on an oriented surface S with unit normal vector $\mathbf{n}$. The surface integral of $\mathbf{F}$ over S is

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_D \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) \, du \, dv$$

for a parametrically defined surface.

2 Evaluate the surface integral $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F} = y\mathbf{i} - x\mathbf{j} + z\mathbf{k}$ and S is the part of the sphere $x^2 + y^2 + z^2 = 4$ in the first octant with inward orientation.

3 Evaluate the surface integral $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F} = \langle x, y, 2z \rangle$ and S is the part of the paraboloid $z = 4 - x^2 - y^2$ that lies above the unit square $[0, 1] \times [0, 1]$ with the *downward* orientation.

4 Evaluate the surface integral $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F} = x\mathbf{i} + y\mathbf{j} + (2x + 2y)\mathbf{k}$ and S is the part of the paraboloid $z = 4 - x^2 - y^2$ that lies above the unit disk (centered at the origin) with upward orientation.

5 Evaluate the surface integral $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F} = \langle -z, x, y \rangle$ and S is the full unit hemisphere (including the base!) on and above the xy -plane (so $x^2 + y^2 + z^2 = 1$ plus a disk) with the outward orientation.

Flux Integrals – Answers and Solutions

1 Here we use the parameterization $\mathbf{r}(x, y) = \langle x, y, 1 - \frac{1}{2}x - \frac{1}{2}y \rangle$. From this we find that

$$\mathbf{r}_x \times \mathbf{r}_y = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & -\frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \end{vmatrix} = \langle \frac{1}{2}, \frac{1}{2}, 1 \rangle.$$

Therefore

$$\iint_S (1 + z) \, dS = \iint_D \left[1 + \left(1 - \frac{1}{2}x - \frac{1}{2}y \right) \right] \, dA.$$

The region D in our parameter space (the xy -plane) need to cover our surface is the triangle

$$D = \{(x, y) : x \geq 0, y \geq 0, x + y \leq 2\},$$

so we can write our limits as follows:

$$\begin{aligned} \iint_S (1 + z) \, dS &= \int_0^2 \int_0^{2-x} \left(2 - \frac{1}{2}x - \frac{1}{2}y \right) \, dy \, dx \\ &= \int_0^2 \left(\frac{1}{4}x^2 - 2x + 3 \right) \, dx \\ &= \frac{1}{12} \cdot 2^3 - 2^2 + 3 \cdot 2 = \frac{8}{3}. \end{aligned}$$

2 This is based on Problem 23 from Section 13.6 of the textbook.

One common parameterization of the sphere of radius a is simply using spherical coordinates (with $\rho = a$):

$$\mathbf{r}(\phi, \theta) = \langle a \sin(\phi) \cos(\theta), a \sin(\phi) \sin(\theta), a \cos(\phi) \rangle.$$

One could then compute $\mathbf{r}_\phi \times \mathbf{r}_\theta$, but it is easier to just remember that we've done this before and the answer is:

$$\mathbf{r}_\phi \times \mathbf{r}_\theta = a^2 \sin(\phi) \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle.$$

(See, for example, page 869 of the text.) The coefficient in front is simply the coefficient $\rho^2 \sin(\phi)$ from the spherical volume element (with $\rho = a$) while the vector is simply the unit vector in the direction $\langle x, y, z \rangle$ (the radial vector, which is perpendicular to the tangent plane to the sphere).

Notice that the orientation is specified to be the *inward* normal, so we actually want $\mathbf{r}_\theta \times \mathbf{r}_\phi = -\mathbf{r}_\phi \times \mathbf{r}_\theta$.

In any case, with this we proceed. In spherical coordinates (with $\rho = a = 2$ in this case), our vector field is

Thus

$$\begin{aligned}
& \mathbf{F} \cdot (\mathbf{r}_\theta \times \mathbf{r}_\phi) \\
&= -4 \sin(\phi) \langle 2 \sin(\phi) \sin(\theta), -2 \sin(\phi) \cos(\theta), 2 \cos(\phi) \rangle \cdot \langle \sin(\phi) \cos(\theta), \sin(\phi) \cos(\theta), \cos(\phi) \rangle \\
&= -8 \sin(\phi) \cos^2(\phi).
\end{aligned}$$

We integrate this over the domain $\{(\phi, \theta) : 0 \leq \phi \leq \pi/2, 0 \leq \theta \leq \pi/2\}$, so we have

$$\begin{aligned}
\iint_S \mathbf{F} \cdot d\mathbf{S} &= \int_0^{\pi/2} \int_0^{\pi/2} -8 \sin(\phi) \cos^2(\phi) \, d\theta \, d\phi \\
&= -4\pi \int_0^{\pi/2} \sin(\phi) \cos^2(\phi) \, d\phi \\
&= -4\pi \left[-\frac{1}{3} \cos^3(\phi) \right]_0^{\pi/2} = -\frac{4\pi}{3}.
\end{aligned}$$

Another approach is to use the parameterization by x and y

$$\mathbf{r}(x, y) = \langle x, y, \sqrt{4 - x^2 - y^2} \rangle$$

then integrating over the quarter circle in the xy -plane. Let's see how this goes:

$$\mathbf{r}_y \times \mathbf{r}_x = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & -\frac{y}{\sqrt{4-x^2-y^2}} \\ 1 & 0 & -\frac{x}{\sqrt{4-x^2-y^2}} \end{vmatrix} = \left\langle -\frac{x}{\sqrt{4-x^2-y^2}}, -\frac{y}{\sqrt{4-x^2-y^2}}, -1 \right\rangle.$$

(Notice we've used $\mathbf{r}_y \times \mathbf{r}_x$ to get the inward-pointing normal.) Thus

$$\begin{aligned}
\mathbf{F} \cdot (\mathbf{r}_y \times \mathbf{r}_x) &= \langle y, -x, z \rangle \cdot \left\langle -\frac{x}{\sqrt{4-x^2-y^2}}, -\frac{y}{\sqrt{4-x^2-y^2}}, -1 \right\rangle \\
&= \left\langle y, -x, \sqrt{4-x^2-y^2} \right\rangle \cdot \left\langle -\frac{x}{\sqrt{4-x^2-y^2}}, -\frac{y}{\sqrt{4-x^2-y^2}}, -1 \right\rangle \\
&= -\sqrt{4-x^2-y^2}
\end{aligned}$$

and so

$$\begin{aligned}
\iint_S \mathbf{F} \cdot d\mathbf{S} &= \int_0^2 \int_0^{\sqrt{4-x^2}} -\sqrt{4-x^2-y^2} \, dy \, dx \\
&= -\int_0^2 \left[\frac{y}{2} \sqrt{4-x^2-y^2} + \frac{4-x^2}{2} \sin^{-1} \left(\frac{y}{\sqrt{4-x^2}} \right) \right]_0^{\sqrt{4-x^2}} dx \\
&= -\frac{\pi}{4} \int_0^2 (4-x^2) \, dx = -\frac{\pi}{4} \cdot \frac{16}{3} = -\frac{4\pi}{3},
\end{aligned}$$

as before.

3 A simple parameterization of this surface is $\mathbf{r}(x, y) = \langle x, y, 4 - x^2 - y^2 \rangle$. Thus

$$\mathbf{r}_x \times \mathbf{r}_y = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & -2x \\ 0 & 1 & -2y \end{vmatrix} = \langle 2x, 2y, 1 \rangle.$$

(Note that this is *not* properly oriented. We're told to use the "downward orientation" but here the $\mathbf{k}$ component is positive. Thus we should be using $\mathbf{r}_y \times \mathbf{r}_x = -\mathbf{r}_x \times \mathbf{r}_y = \langle -2x, -2y, -1 \rangle$.) Thus

$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \iint_D \langle x, y, 2z \rangle \cdot \langle -2x, -2y, -1 \rangle \, dx \, dy \\ &= \iint_D (-2x^2 - 2y^2 - 2z) \, dx \, dy. \end{aligned}$$

Now we notice that (according to our parameterization) $z = 4 - x^2 - y^2$. The region D in our parameter space is a unit square, so we get

$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \int_0^1 \int_0^1 [-2x^2 - 2y^2 - 2(4 - x^2 - y^2)] \, dx \, dy \\ &= \int_0^1 \int_0^1 (-8) \, dx \, dy = -8 \text{ Area}(D) = -8. \end{aligned}$$

4 One way to do this is to use the parameterization $\mathbf{r}(x, y) = \langle x, y, 4 - x^2 - y^2 \rangle$, so $\mathbf{r}_x = \langle 1, 0, -2x \rangle$, $\mathbf{r}_y = \langle 0, 1, -2y \rangle$, and so

$$\mathbf{r}_x \times \mathbf{r}_y = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & -2x \\ 0 & 1 & -2y \end{vmatrix} = \langle 2x, 2y, 1 \rangle.$$

Thus we can write

$$\mathbf{F} \cdot (\mathbf{r}_x \times \mathbf{r}_y) = \langle x, y, 2x + 2y \rangle \cdot \langle 2x, 2y, 1 \rangle = 2x^2 + 2y^2 + 2x + 2y.$$

Hence our flux is

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D (2x^2 + 2y^2 + 2x + 2y) \, dx \, dy,$$

where D is the unit disk. Thus we make the change to polar coordinates, where $2x^2 + 2y^2 + 2x + 2y = 2r^2 + 2r(\cos(\theta) + \sin(\theta))$ and $dx \, dy = r \, dr \, d\theta$. We get

$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \int_0^{2\pi} \int_0^1 \left[2r^2 + 2r(\cos(\theta) + \sin(\theta)) \right] r \, dr \, d\theta \\ &= \int_0^{2\pi} \int_0^1 \left[2r^3 + 2r^2(\cos(\theta) + \sin(\theta)) \right] \, dr \, d\theta \\ &= \int_0^{2\pi} \left[\frac{1}{2} + \frac{2}{3}(\cos(\theta) + \sin(\theta)) \right] \, d\theta \\ &= \left[\frac{1}{2}\theta + \frac{2}{3}(\sin(\theta) - \cos(\theta)) \right]_0^{2\pi} = \pi. \end{aligned}$$

Another approach is to use polar coordinates to parameterize the surface from the very beginning. That is, we could use the parameterization $\mathbf{r}(r, \theta) = \langle r \cos(\theta), r \sin(\theta), 4 - r^2 \rangle$, in which case $\mathbf{r}_r = \langle \cos(\theta), \sin(\theta), -2r \rangle$ and $\mathbf{r}_\theta = \langle -r \sin(\theta), r \cos(\theta), 0 \rangle$, so

$$\mathbf{r}_r \times \mathbf{r}_\theta = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos(\theta) & \sin(\theta) & -2r \\ -r \sin(\theta) & r \cos(\theta) & 0 \end{vmatrix} = \langle 2r^2 \cos(\theta), 2r^2 \sin(\theta), r \rangle.$$

In these coordinates our vector field is $\mathbf{F} = \langle r \cos(\theta), r \sin(\theta), 2r(\cos(\theta) + \sin(\theta)) \rangle$, and therefore our flux is

$$\begin{aligned} \iint_S \mathbf$$

5 Here we need to compute two integrals:

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_{S_1} \mathbf{F} \cdot d\mathbf{S} + \iint_{S_2} \mathbf{F} \cdot d\mathbf{S},$$

where S_1 is the hemisphere (with outward-pointing normal) and S_2 is the unit disk in the xy -plane (with downward-pointing normal).

The integral over S_1 is very similar to the previous problem. We'll use the first parameterization of Problem 3, namely

$$\mathbf{r}(\phi, \theta) = \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle.$$

This gives us an outward-pointing normal

$$\mathbf{r}_\phi \times \mathbf{r}_\theta = \sin(\phi) \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle,$$

so

$$\begin{aligned} & \mathbf{F} \cdot (\mathbf{r}_\phi \times \mathbf{r}_\theta) \\ &= \langle -\cos(\phi), \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta) \rangle \cdot \langle \sin^2(\phi) \cos(\theta), \sin^2(\phi) \sin(\theta), \sin(\phi) \cos(\phi) \rangle \\ &= -\sin^2(\phi) \cos(\phi) \cos(\theta) + \sin^3(\phi) \sin(\theta) \cos(\theta) + \sin^2(\phi) \cos(\phi) \sin(\theta). \end{aligned}$$

Thus

$$\begin{aligned} & \iint_{S_1} \mathbf{F} \cdot d\mathbf{S} \\ &= \int_0^{\pi/2} \int_0^{2\pi} (-\sin^2(\phi) \cos(\phi) \cos(\theta) + \sin^3(\phi) \sin(\theta) \cos(\theta) + \sin^2(\phi) \cos(\phi) \sin(\theta)) \, d\theta \, d\phi \\ &= \int_0^{\pi/2} \left(-\sin^2(\phi) \cos(\phi) \sin(\theta) - \sin^3(\phi) \cdot \frac{1}{2} \sin^2(\theta) - \sin^2(\phi) \cos(\phi) \cos(\theta) \right) \Big|_{\theta=0}^{2\pi} d\phi \\ &= 0. \end{aligned}$$

The second integral is even simpler. Here S_2 is the unit disk in the xy -plane, with the unit normal $\mathbf{n} = -\mathbf{k}$ (straight down). Thus

$$\iint_{S_2} \mathbf{F} \cdot d\mathbf{S} = \iint_D \langle -z, x, y \rangle \cdot \langle 0, 0, -1 \rangle \, dA = \iint_D -y \, dA,$$

where D is the unit disk in the xy -plane. We use polar coordinates to compute this integral:

$$\begin{aligned} \iint_{S_2} \mathbf{F} \cdot d\mathbf{S} &= \iint_D -y \, dA = \int_0^1 \int_0^{2\pi} -r \sin(\theta) \cdot r \, d\theta \, dr \\ &= \int_0^1 r^2 \cos(\theta) \Big|_0^{2\pi} dr = 0. \$$

Thus the full integral is

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_{S_1} \mathbf{F} \cdot d\mathbf{S} + \iint_{S_2} \mathbf{F} \cdot d\mathbf{S} = 0 + 0 = 0.$$

We'll see a simpler way of computing this integral on Wednesday when we learn about the Divergence Theorem.