

① DATA gives inconsistent system  $\begin{cases} a-b+c = -2 \\ a-b+c = -1 \\ a = 0 \\ a+b+c = -1 \\ a+b+c = -2 \end{cases} \Rightarrow \begin{bmatrix} 1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 0 \\ -1 \\ -2 \end{bmatrix}$

$\Rightarrow A \vec{c} = \vec{y}$

Solutions given by normal equation  $A^T A \vec{c} = A^T \vec{y}$

calculate  $A^T A = \begin{bmatrix} 5 & 0 & 4 \\ 0 & 4 & 0 \\ 4 & 0 & 4 \end{bmatrix}$   $A^T \vec{y} = \begin{bmatrix} -6 \\ -6 \\ -6 \end{bmatrix}$  solve  $\left[ \begin{array}{ccc|c} 5 & 0 & 4 & -6 \\ 0 & 4 & 0 & -6 \\ 4 & 0 & 4 & -6 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -3/2 \end{array} \right]$

so  $f(x) = 0 + 0x - \frac{3}{2}x^2 = -\frac{3}{2}x^2$

② expand along 2nd column

$\det A = 2 \det \begin{bmatrix} 2 & 1 & 0 & 3 \\ -4 & 2 & -1 & 0 \\ 3 & -3 & 0 & 0 \\ -3 & 1 & 0 & 0 \end{bmatrix} = 2 \cdot 3 \det \begin{bmatrix} -4 & 2 & -1 \\ 3 & -3 & 0 \\ -3 & 1 & 0 \end{bmatrix} = 2 \cdot 3 \cdot (-1) [3 - 9] = (-6)(-6) = \boxed{36}$

②b Subtract 1st row from all other rows  $\rightarrow$  same determinant.

$\Rightarrow \begin{bmatrix} a & b & -b & \dots & \dots & \dots & b \\ 0 & a-b & 0 & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & 0 \\ 0 & a-b & a-b & \dots & \dots & \dots & (a-b) \end{bmatrix} = a \cdot (a-b)^7$

Since  $7 \times 7$  MATRIX IS LOWER TRIANGULAR,  $\det = \text{prod. of its diagonal entries.}$

If  $a=1, b=-1 \Rightarrow \det A = 2^7 \neq 0$

so  $A$  will be invertible

③a  $\|\vec{v}_1\| = \sqrt{6}$  b  $\sqrt{\det A^T A}$  where  $A = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & -2 \\ 2 & 1 \end{bmatrix}$   $A^T A = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$

c  $\vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 2 \end{bmatrix}$

$\vec{v}_2 \cdot \vec{w}_1 = 0$ , so  $\vec{w}_2 = \frac{\vec{v}_2}{\|\vec{v}_2\|} = \frac{1}{\sqrt{6}} \begin{bmatrix} 0 \\ -2 \\ 1 \\ -1 \end{bmatrix}$

Area =  $\sqrt{\det A^T A} = \sqrt{36} = 6$

$\vec{v}_3 \cdot \vec{w}_1 = 0, \vec{v}_3 \cdot \vec{w}_2 = \sqrt{6}$ , so  $\vec{v}_3 - (\vec{v}_3 \cdot \vec{w}_1) \vec{w}_1 - (\vec{v}_3 \cdot \vec{w}_2) \vec{w}_2 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0 \end{bmatrix} \Rightarrow \vec{w}_3 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0 \end{bmatrix}$

d  $BB^T =$  Projection onto  $\text{span}\{\vec{w}_1, \vec{w}_2\}$  which is 2D in  $\mathbb{R}^4$ .  
The orthonormal are therefore  $\{+1, +1, 0, 0\}$ .  $E_1 = \text{Span}\{\vec{w}_1, \vec{w}_2\} = W$   
 $E_0 = W^\perp$

④  $\vec{x}(t+1) = A \vec{x}(t) \Rightarrow \vec{x}(t) = A^t \vec{x}(0)$

a  $\lambda I - A = \begin{bmatrix} \lambda-1 & 1 \\ -1 & \lambda-1 \end{bmatrix}$   $\det = \lambda^2 - 2\lambda + 2 = 0 \Rightarrow \lambda = 1 \pm i$  eigenvalues

$\lambda = 1+i \Rightarrow \begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \vec{w} = \begin{bmatrix} 1 \\ -i \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \vec{u} + i \vec{v}$   $B = \begin{bmatrix} \vec{u} & \vec{v} \end{bmatrix}$

$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$   $P^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$   $P^{-1} A P \Rightarrow A$  already in form  $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

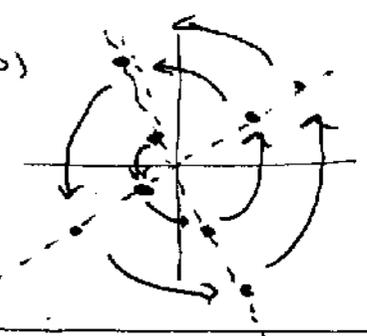
a ROTATION-DILATION MATRIX  $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \sqrt{2} R_{\pi/4}$



where  $R_{\pi/4} =$  ROTATION through  $\pi/4$ , counterclockwise.

next  $\rightarrow$

4 cart.  $A^t = (\sqrt{2})^t R_{t \cdot \frac{\pi}{4}}$   $\vec{x}(t) = (\sqrt{2})^t R_{t \cdot \frac{\pi}{4}} \vec{x}(0)$   
 (SPIRAL OUT)



①  $\vec{x}(12) = (\sqrt{2})^{12} R_{3\pi} \begin{bmatrix} -1 \\ +2 \end{bmatrix} = 64 \begin{bmatrix} -1 \\ -2 \end{bmatrix} = \begin{bmatrix} -64 \\ -128 \end{bmatrix}$

Trajectory does enter all four quadrants.

⑤②  $A \vec{x}_0 = \vec{x}_1$   $B = \{ \vec{x}_0, \vec{x}_1, \vec{x}_2 \} \Rightarrow [A]_B = \begin{bmatrix} 0 & 0 & a \\ 1 & 0 & b \\ 0 & 1 & 0 \end{bmatrix}$   
 $A \vec{x}_1 = \vec{x}_2$   
 $A \vec{x}_2 = \vec{x}_3 = a \vec{x}_0 + b \vec{x}_1$

⑥  $\vec{x}_0 = \begin{bmatrix} 0 \\ 0 \\ 1/2 \end{bmatrix}$   $\vec{x}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$   $\vec{x}_2 = \begin{bmatrix} 0 \\ -5 \\ 0 \end{bmatrix} \Rightarrow P = \begin{bmatrix} 0 & 3 & 0 \\ 0 & 0 & -5 \\ 1/2 & 0 & 0 \end{bmatrix}$   $P^{-1} = \begin{bmatrix} 0 & 0 & 2 \\ 1/3 & 0 & 0 \\ 0 & -1/5 & 0 \end{bmatrix}$

$[A]_B = P^{-1} A P \Rightarrow A = P [A]_B P^{-1}$

$\vec{x}_3 = \begin{bmatrix} 9 \\ 0 \\ 1 \end{bmatrix} = A \vec{x}_2$   $\Rightarrow 3b = 9 \Rightarrow b = 3$   
 $\Rightarrow a/2 = 1 \Rightarrow a = 2$

$= a \vec{x}_0 + b \vec{x}_1 = a \begin{bmatrix} 0 \\ 0 \\ 1/2 \end{bmatrix} + b \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 3b \\ 0 \\ a/2 \end{bmatrix} \Rightarrow [A]_B = \begin{bmatrix} 0 & 0 & 2 \\ 1 & 0 & 3 \\ 0 & 1 & 0 \end{bmatrix}$

so  $A = \begin{bmatrix} 0 & 3 & 0 \\ 0 & 0 & -5 \\ 1/2 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 2 \\ 1 & 0 & 3 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 2 \\ 1/3 & 0 & 0 \\ 0 & -1/5 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -9/5 & 6 \\ -5/3 & 0 & 0 \\ 0 & -1/5 & 0 \end{bmatrix}$

⑦  $\vec{x}(t+1) = A \vec{x}(t)$   $A = \begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix}$   $\lambda I - A = \begin{bmatrix} \lambda - .8 & -.3 \\ -.2 & \lambda - .7 \end{bmatrix}$

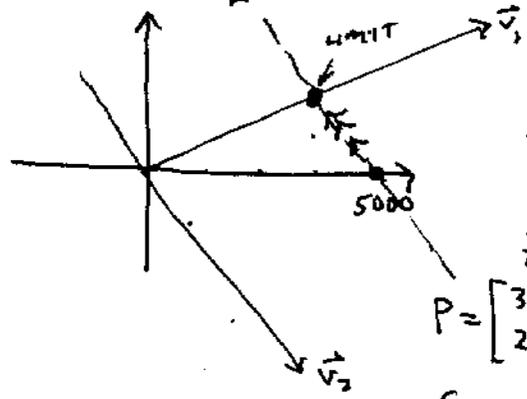
$\vec{x}(0) = \begin{bmatrix} 5000 \\ 0 \end{bmatrix}$

$\Rightarrow \lambda^2 - \frac{3}{2}\lambda + \frac{1}{2} = 0$   $\lambda_1 = 1$   
 $(\lambda - 1)(\lambda - \frac{1}{2}) = 0$   $\lambda_2 = \frac{1}{2}$

$\lambda_1 = 1 \Rightarrow \begin{bmatrix} .2 & -.3 & | & 0 \\ -.2 & .3 & | & 0 \end{bmatrix} \rightarrow \vec{v}_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$

$\lambda_2 = \frac{1}{2} \Rightarrow \begin{bmatrix} -.3 & -.3 & | & 0 \\ -.2 & -.2 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & | & 0 \\ 0 & | & 0 \end{bmatrix}$

$\Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$



$\vec{x}(t) = c_1 \lambda_1^t \vec{v}_1 + c_2 \lambda_2^t \vec{v}_2 = c_1 \vec{v}_1 + c_2 (\frac{1}{2})^t \vec{v}_2$   
 $\lim_{t \rightarrow +\infty} \vec{x}(t) = c_1 \vec{v}_1$

$P = \begin{bmatrix} 3 & 1 \\ 2 & -1 \end{bmatrix}$   $P^{-1} = \frac{1}{5} \begin{bmatrix} +1 & +1 \\ +2 & -3 \end{bmatrix}$   $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = P^{-1} \begin{bmatrix} 5000 \\ 0 \end{bmatrix} = \frac{5000}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1000 \\ 2000 \end{bmatrix}$

$c_1 = 1000 \therefore \vec{x}(t) \rightarrow \begin{bmatrix} 3000 \\ 2000 \end{bmatrix} = \begin{bmatrix} \text{MEGAMART} \\ \text{BROADWAY} \end{bmatrix}$