

4.3

34) Given $M, N \in \mathcal{H}$ w/ $M = \begin{pmatrix} p & -q & -r & -s \\ q & p & s & -r \\ r & -s & p & q \\ s & r & -q & p \end{pmatrix}$, $N = \begin{pmatrix} a & -b & -c & -d \\ b & a & d & -c \\ c & -d & a & b \\ d & c & -b & a \end{pmatrix}$

a) Let $p' = p + a$
 $q' = q + b$
 $r' = r + c$
 $s' = s + d$

Then,
 $M + N = \begin{pmatrix} p' & -q' & -r' & -s' \\ q' & p' & s' & -r' \\ r' & -s' & p' & q' \\ s' & r' & -q' & p' \end{pmatrix} \in \mathcal{H}$

b) Given $k \in \mathbb{R}$,
 Let $p' = kp$
 $q' = kq$
 $r' = kr$
 $s' = ks$

Then,
 $kM = \begin{pmatrix} p' & -q' & -r' & -s' \\ q' & p' & s' & -r' \\ r' & -s' & p' & q' \\ s' & r' & -q' & p' \end{pmatrix} \in \mathcal{H}$

c) Let $p' = pa - qb - rc - sd$
 $q' = qa + pb + sc - rd$
 $r' = ra - sb + pc + qd$
 $s' = sa + rb - qc + pd$

Then,
 $MN = \begin{pmatrix} p' & -q' & -r' & -s' \\ q' & p' & s' & -r' \\ r' & -s' & p' & q' \\ s' & r' & -q' & p' \end{pmatrix} \in \mathcal{H}$

d) $\begin{pmatrix} A & -B^T \\ B & A^T \end{pmatrix}^T = \begin{pmatrix} A^T & B^T \\ (-B^T)^T & (A^T)^T \end{pmatrix} = \begin{pmatrix} A^T & B^T \\ -B & A \end{pmatrix} \in \mathcal{H}$

e) $M^T M = (p^2 + q^2 + r^2 + s^2) I_4$

f) if $M \neq 0$, $\left(\frac{1}{p^2 + q^2 + r^2 + s^2} M^T \right) M = I_4$

\therefore as M is square & has a left inverse, it is invertible

w/ $M^{-1} = \frac{1}{p^2 + q^2 + r^2 + s^2} M^T$

by (b) & (d), $M^{-1} \in \mathcal{H}$.

g) No. Consider $M = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}$ & $N = \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$. $MN \neq NM$.

4.4

10)

a) Given \vec{x} s.t. $A\vec{x} = \vec{b}$ (such \vec{x} exists as $A\vec{x} = \vec{b}$ is consistent)

$$\text{Let } \vec{x}_h = \text{proj}_{\ker(A)} \vec{x}$$

$$\text{Let } \vec{x}_o = \vec{x} - \vec{x}_h.$$

$$\text{Claim: } A\vec{x}_o = \vec{b}$$

$$\text{Pf: } A\vec{x}_o = A(\vec{x} - \vec{x}_h)$$

$$= A\vec{x} - A\vec{x}_h$$

$$= \vec{b} - \vec{0}$$

$$= \vec{b}.$$

as $\vec{x}_h \in \ker(A)$

$$\text{Claim: } \vec{x}_o \in (\ker(A))^\perp$$

Pf:

$$\vec{x}_h = \text{proj}_{\ker(A)} \vec{x}$$

$$\vec{x}_o = \vec{x} - \text{proj}_{\ker(A)} \vec{x} \Rightarrow \vec{x}_o \perp \vec{x}_h$$

\therefore as $\vec{x}_h \in \ker(A)$, $\vec{x}_o \in (\ker(A))^\perp$ \square

b) Suppose $\vec{x}, \vec{y} \in (\ker(A))^\perp$ & $A\vec{x} = A\vec{y} = \vec{b}$.

Now, $\ker(A)$ is a subspace by Fact 3.2.2

$\Rightarrow (\ker(A))^\perp$ is a subspace by Fact 4.1.5

$$\therefore \vec{x}, \vec{y} \in (\ker(A))^\perp \Rightarrow \vec{x} - \vec{y} \in (\ker(A))^\perp$$

$$\text{Furthermore, } A(\vec{x} - \vec{y}) = A\vec{x} - A\vec{y} = \vec{b} - \vec{b} = \vec{0}$$

$$\therefore \vec{x} - \vec{y} \in \ker(A).$$

$$\text{Hence, } \vec{x} - \vec{y} = \vec{0}.$$

$$\therefore \vec{x} = \vec{y} \quad \square$$

c) Given \vec{x}_1 s.t. $A\vec{x}_1 = \vec{b}$.

Let \vec{x}_o be the solution to $A\vec{x} = \vec{b}$ in $(\ker(A))^\perp$.

$$\text{by part (a) } \vec{x}_1 = \vec{x}_o + \vec{x}_h \quad \text{w/ } \vec{x}_o \perp \vec{x}_h$$

$$\therefore \text{ by Pythagorean Thm } \|\vec{x}_1\|^2 = \|\vec{x}_o\|^2 + \|\vec{x}_h\|^2$$

$$\Rightarrow \|\vec{x}_1\|^2 \geq \|\vec{x}_o\|^2$$

$$\Rightarrow \|\vec{x}_1\| \geq \|\vec{x}_o\| \quad \square$$

4.4

$$22) \vec{x}^* = (A^T A)^{-1} A^T \vec{b} = \begin{pmatrix} 3 \\ -2 \end{pmatrix}$$

$$A \vec{x}^* = \vec{b} \Rightarrow \|\vec{b} - A \vec{x}^*\| = 0.$$

$$26) A^T A \vec{x}^* = A^T \vec{b}$$

$$\Rightarrow \begin{pmatrix} 66 & 78 & 90 \\ 78 & 93 & 108 \\ 90 & 108 & 126 \end{pmatrix} \begin{pmatrix} x_1^* \\ x_2^* \\ x_3^* \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \Rightarrow \vec{x}^* = \begin{pmatrix} t - 7/6 \\ 1 - 2t \\ t \end{pmatrix} \text{ where } t \text{ is an arbitrary constant.}$$

$$32) \begin{pmatrix} 1 & t & t^2 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} f(t) \\ 27 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\therefore \begin{pmatrix} c_0^* \\ c_1^* \\ c_2^* \end{pmatrix} = \left[\begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}^T \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \right]^{-1} \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}^T \begin{pmatrix} 27 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 25.65 \\ -28.35 \\ 6.75 \end{pmatrix}$$

$$\therefore f(t) \approx 25.65 - 28.35t + 6.75t^2$$

41) a) We want $\begin{pmatrix} c_0 \\ c_1 \end{pmatrix}$ s.t. $\log D = c_0 + c_1 t$ (t in years since 1970)

$$\begin{pmatrix} 1 & 0 \\ 1 & 5 \\ 1 & 10 \\ 1 & 15 \\ 1 & 20 \\ 1 & 25 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \begin{pmatrix} \log 370 \\ \log 533 \\ \log 908 \\ \log 1823 \\ \log 3233 \\ \log 4871 \end{pmatrix} \Rightarrow \begin{pmatrix} c_0^* \\ c_1^* \end{pmatrix} = \begin{pmatrix} 2.53 \\ 0.047 \end{pmatrix}$$

$$\therefore \log D \approx 2.53 + 0.047t$$

$$\Rightarrow D \approx 339 \cdot 10^{0.047t}$$

b) in 2020, $t=50 \Rightarrow D = 76,000$.

Projected debt is \$76 trillion.

5.1

$$16) \det \begin{pmatrix} 0 & 0 & 2 & 3 & 1 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 9 & 7 & 9 & 3 \\ 0 & 0 & 0 & 0 & 5 \\ 3 & 4 & 5 & 8 & 5 \end{pmatrix} = 3 \det \begin{pmatrix} 0 & 2 & 3 & 1 \\ 0 & 0 & 2 & 2 \\ 9 & 7 & 9 & 3 \\ 0 & 0 & 0 & 5 \end{pmatrix} = 3 \cdot 5 \cdot \det \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 9 & 7 & 9 \end{pmatrix}$$

$$= -3 \cdot 5 \cdot 2 \cdot \det \begin{pmatrix} 0 & 2 \\ 9 & 7 \end{pmatrix} = -30 [0 \cdot 7 - 9 \cdot 2] = \boxed{540}$$

$$21) \det \begin{pmatrix} 7 & 6 \\ 9 & 8 \end{pmatrix} = 7 \cdot 8 - 6 \cdot 9 = 2. \quad \det \neq 0 \therefore \text{the matrix is invertible}$$

$$22) \det \begin{pmatrix} 3 & 2 \\ 6 & 4 \end{pmatrix} = 12 - 12 = 0. \quad \therefore \text{the matrix is not invertible.}$$

$$23) \det \begin{pmatrix} a & b & c \\ 0 & b & c \\ 0 & 0 & c \end{pmatrix} = abc \quad \therefore \text{invertible if } a \neq 0, b \neq 0, \& c \neq 0$$

$$24) \det \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} = 0 \quad \therefore \text{not invertible}$$

$$25) \det \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 7 \end{pmatrix} = 6 \quad \therefore \text{invertible}$$

$$28) \det (\lambda I - A) = \det \begin{pmatrix} \lambda - 2 & 3 \\ -3 & \lambda - 2 \end{pmatrix} = \lambda^2 + 4\lambda + 13 > 0 \quad \forall \lambda \in \mathbb{R}$$

$\therefore \lambda I - A$ is invertible for all real λ .

$$46) \det [\vec{u} \ \vec{v} \ \vec{w}] = \vec{u} \cdot (\vec{v} \times \vec{w}) \quad \text{for any } 3 \times 3 \text{ matrix } [\vec{u} \ \vec{v} \ \vec{w}].$$

$$\therefore \det(A) = (\vec{v} \times \vec{w}) \cdot (\vec{v} \times \vec{w}) = \|\vec{v} \times \vec{w}\|^2.$$

A is invertible if $\vec{v} \times \vec{w} \neq 0$, i.e. if \vec{v} & \vec{w} are not parallel.

5.2

$$6) \det(M_n) = \det \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 2 & \dots & 2 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 2 & 3 & \dots & n \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 2 & \dots & 2 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 2 & \dots & n-1 \\ 0 & 0 & \dots & 0 & 1 \end{pmatrix}$$

we obtain this matrix by subtracting next to last row from the last row

$$= \det(M_{n-1})$$

$$\text{But, } \det(M_1) = \det(1) = 1$$

$$\therefore \boxed{\det(M_n) = 1 \quad \forall n \in \mathbb{N}}$$

5.220) a) A is invertible

$$\Rightarrow \text{rref}(A) = I_n$$

$$\Rightarrow \text{rref}[A:AB] = [I_n:M] \text{ for some matrix } M.$$

$$\text{Now, } \forall i \quad [A:AB] \begin{bmatrix} B\vec{e}_i \\ -\vec{e}_i \end{bmatrix} = AB\vec{e}_i - A\vec{e}_i = 0$$

$$\therefore \begin{bmatrix} B\vec{e}_i \\ -\vec{e}_i \end{bmatrix} \in \text{ker}[A:AB] \quad \forall i$$

$$\Rightarrow \begin{bmatrix} B\vec{e}_i \\ -\vec{e}_i \end{bmatrix} \in \text{ker}[I_n:M] \quad \forall i$$

$$\therefore [I_n:M] \begin{bmatrix} B\vec{e}_i \\ -\vec{e}_i \end{bmatrix} = B\vec{e}_i - M\vec{e}_i = 0 \quad \forall i$$

$$\Rightarrow B\vec{e}_i = M\vec{e}_i \quad \forall i$$

Thus, B & M have identical columns.

Hence, $B = M$.

$$\therefore \text{rref}[A:AB] = [I_n:B] \quad \square$$

b) if $B = A^{-1}$ we get

$$\text{rref}[A:I_n] = [I_n:A^{-1}]$$

which justifies the method of finding an inverse that we have been using.

5.2

8) $T(\vec{x}) = 0 \iff \vec{x}$ is a lin. combination of v_i 's
 i.e. $\iff \vec{x} \in \text{span}\{\vec{v}_2, \dots, \vec{v}_n\}$.

$$\therefore \boxed{\ker(T) = \text{span}\{\vec{v}_2, \dots, \vec{v}_n\}}$$

\det is a mapping from the space of $n \times n$ matrices to \mathbb{R}

$$\therefore \boxed{\text{Im}(T) = \mathbb{R}}$$

Hence,

$$\boxed{\begin{aligned} \dim(\ker(T)) &= n-1 \\ \dim(\text{Im}(T)) &= 1 \end{aligned}}$$

30) a) Claim: $\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n \neq 0 \iff \{\vec{v}_2, \vec{v}_3, \dots, \vec{v}_n\}$ is lin. ind.
 Suppose $\{\vec{v}_2, \vec{v}_3, \dots, \vec{v}_n\}$ are lin. ind. Choose an $\vec{x} \notin \text{span}\{\vec{v}_2, \dots, \vec{v}_n\}$.
 So, $\{\vec{x}, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis of \mathbb{R}^n

$$\therefore \det[\vec{x} \ \vec{v}_2 \ \dots \ \vec{v}_n] = \vec{x} \cdot (\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n) \neq 0$$

$$\Rightarrow \vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n \neq 0$$

Now, suppose $\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n = 0$. Say the i th component of this vector is non-zero. Then $\vec{e}_i \cdot (\vec{v}_2 \times \dots \times \vec{v}_n) = \det[\vec{e}_i \ \vec{v}_2 \ \dots \ \vec{v}_n] \neq 0$

$\therefore \{\vec{v}_2, \dots, \vec{v}_n\}$ is lin. ind.

$$\text{b) } \vec{e}_2 \times \vec{e}_3 \times \dots \times \vec{e}_n = \det \begin{bmatrix} \vec{e}_i & \vec{e}_2 & \dots & \vec{e}_n \end{bmatrix} = \begin{cases} 1 & \text{if } i=1 \\ 0 & \text{if } i>1 \end{cases}$$

$$\therefore \vec{e}_2 \times \vec{e}_3 \times \dots \times \vec{e}_n = \vec{e}_1$$

$$\text{c) } \vec{v}_i \cdot (\vec{v}_2 \times \dots \times \vec{v}_n) = \det(\vec{v}_i \ \vec{v}_2 \ \dots \ \vec{v}_n) = 0 \quad \forall i \in \{2, 3, \dots, n\} \text{ as}$$

the matrix has 2 identical columns.

$$\text{d) } \det \begin{pmatrix} \vec{e}_i & \vec{v}_2 & \vec{v}_3 & \dots & \vec{v}_n \end{pmatrix} = -\det \begin{pmatrix} \vec{e}_i & \vec{v}_3 & \vec{v}_2 & \dots & \vec{v}_n \end{pmatrix}$$

$$\therefore \vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n = -\vec{v}_3 \times \vec{v}_2 \times \dots \times \vec{v}_n$$

5.2

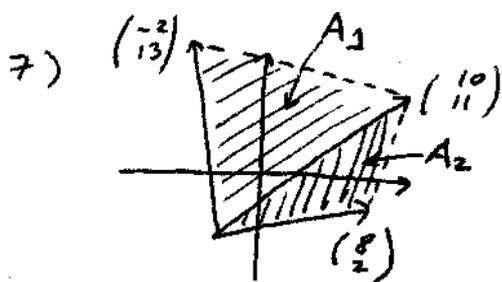
30) e)
$$\det \begin{bmatrix} \vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n & \vec{v}_2 & \vec{v}_3 & \dots & \vec{v}_n \end{bmatrix} = (\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n) \cdot (\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n)$$

$$= \|\vec{v}_2 \times \vec{v}_3 \times \dots \times \vec{v}_n\|^2.$$

f) see page 240 of Bretscher.

5.3

2) By Fact 5.3.3 Area = $\frac{1}{2} \left| \det \begin{pmatrix} 3 & 8 \\ 7 & 2 \end{pmatrix} \right| = \frac{1}{2} |-50| = \boxed{25}$



Area = $A_1 + A_2$

$$= \frac{1}{2} \left| \det \begin{pmatrix} 10 & -2 \\ 11 & 13 \end{pmatrix} \right| + \frac{1}{2} \left| \det \begin{pmatrix} 8 & 10 \\ 2 & 11 \end{pmatrix} \right| = \boxed{110}.$$

14) By Fact 5.3.7
$$V = \left\{ \det \left[\begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 1 & 3 \\ 0 & 1 & 4 \end{pmatrix} \right] \right\}^{1/2} = \left\{ \det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 4 & 10 \\ 1 & 10 & 30 \end{pmatrix} \right\}^{1/2}$$

$$= \boxed{\sqrt{6}}$$

17) a) Let $\vec{w} = \vec{v}_1 \times \vec{v}_2 \times \vec{v}_3$.

Note that $\vec{w} \perp \vec{v}_i$ for $i=1,2,3$. (see 5.20.30c)

Now, $V(\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{w}) = V(\vec{v}_1, \vec{v}_2, \vec{v}_3) \|\vec{w} - \text{proj}_{V_3} \vec{w}\|$ by Def 5.3.6

$$= V(\vec{v}_1, \vec{v}_2, \vec{v}_3) \|\vec{w}\| \text{ as } \text{proj}_{V_3} \vec{w} = 0 \text{ since } \vec{w} \perp \vec{v}_i \forall i.$$

b)
$$V(v_1, v_2, v_3, \vec{v}_1 \times \vec{v}_2 \times \vec{v}_3) = \left| \det [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3 \ \vec{v}_1 \times \vec{v}_2 \times \vec{v}_3] \right|$$

$$= \left| \det [\vec{v}_1 \times \vec{v}_2 \times \vec{v}_3 \ \vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] \right|$$

$$= \|\vec{v}_1 \times \vec{v}_2 \times \vec{v}_3\|^2 \text{ by 5.2.30e}$$

c) by a & b $V(\vec{v}_1, \vec{v}_2, \vec{v}_3) = \|\vec{v}_1 \times \vec{v}_2 \times \vec{v}_3\|$.
 if $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is lin. dependent, both sides of the equation are 0
 by Exercise 15 & Exercise 5.2.30a

5.3

$$25) [\text{adj}(A)]_{ij} = (-1)^{i+j} \det(A_{ji})$$

$$\Rightarrow \text{adj}(A) = \begin{pmatrix} 1 & 0 & -1 \\ 0 & -1 & 0 \\ -2 & 0 & 1 \end{pmatrix}.$$

$$\therefore A^{-1} = \frac{1}{\det(A)} \text{adj}(A) = \frac{1}{-1} \begin{pmatrix} 1 & 0 & -1 \\ 0 & -1 & 0 \\ -2 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 2 & 0 & -1 \end{pmatrix}.$$