

HW # 19

6.4/36

6.5/5, 8, 12, 22, 28, 40afg, 42

6.4

36. a. Entries in the first row are age-specific birth rates
Entries immediately below diagonal are age-specific survival rates.

For example, during the next 15 years, 15-30 year olds will, on average, have 1.6 surviving child per person. 89% of people in this age bracket will themselves survive to become 30-45 years old 15 years in the future.

$$b. \lambda_1 = 1.908 \quad \vec{v}_1 = \begin{bmatrix} .574 \\ .247 \\ .115 \\ .047 \\ .014 \\ .002 \end{bmatrix}$$

\vec{v}_1 gives the long run population distribution

λ_1 gives the long run population growth rate.

annual growth factor = $\sqrt[15]{1.908} \approx 1.044$ or 4.4% growth

6.5

$$5. A = \begin{bmatrix} .5 & .6 \\ -.3 & 1.4 \end{bmatrix}$$

$$\lambda_1 = 0.8$$

$$\lambda_2 = 1.1 > 1 \Rightarrow \vec{0} \text{ is not stable}$$

Note: This problem was not assigned

$$8. A = \begin{bmatrix} 1 & -0.2 \\ 0.1 & 0.7 \end{bmatrix}$$

$$\lambda_1 = 0.9$$

$$\lambda_2 = 0.8$$

$\left. \begin{array}{l} \lambda_1 = 0.9 \\ \lambda_2 = 0.8 \end{array} \right\} < 1 \Rightarrow \vec{0} \text{ is stable state}$

12. $A = \begin{bmatrix} 0.6 & K \\ -K & 0.6 \end{bmatrix}$

$\lambda_{1,2} = 0.6 \pm iK$

stable iff $|\lambda_1| = |\lambda_2| = \sqrt{0.36 + K^2} < 1$

$\Rightarrow K^2 < .64$

$|K| < 0.8$

22. $A = \begin{bmatrix} 7 & -15 \\ 6 & -11 \end{bmatrix}$

Find e-values:

$\det \begin{bmatrix} \lambda-7 & 15 \\ -6 & \lambda+11 \end{bmatrix} = (\lambda-7)(\lambda+11) + 90 = \lambda^2 + 4\lambda + 13 = 0$

$\lambda = \frac{-4 \pm \sqrt{16 - 52}}{2}$

$\lambda = -2 \pm 3i, r = \sqrt{13}, \phi \approx 2.16$

Find e-vectors:

$\begin{bmatrix} -9+3i & 15 \\ -6 & 9+3i \end{bmatrix} \xrightarrow{+(-9+3i)} \begin{bmatrix} 90 & -135-45i \\ -6 & 9+3i \end{bmatrix} \xrightarrow{\div 15} \begin{bmatrix} 6 & -9-3i \\ -6 & 9+3i \end{bmatrix} \rightarrow \begin{bmatrix} 2 & -3-i \\ 0 & 0 \end{bmatrix}$

$\vec{v}_1 = \begin{bmatrix} 3+i \\ 2 \end{bmatrix}$

$\vec{v}_{1,2} = \begin{bmatrix} 3 \\ 2 \end{bmatrix} \pm \begin{bmatrix} 1 \\ 0 \end{bmatrix} i$

$\vec{y} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{x} = \begin{bmatrix} 3 \\ 2 \end{bmatrix} \quad c_1 \vec{y} + c_2 \vec{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow c_1 = -3/2, c_2 = 1/2$

$x(t) = (\sqrt{13})^t \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} \cos \phi t & -\sin \phi t \\ \sin \phi t & \cos \phi t \end{bmatrix} \begin{bmatrix} -3/2 \\ 1/2 \end{bmatrix}$

$x(t) = (\sqrt{13})^t \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} -3/2 \cos \phi t - 1/2 \sin \phi t \\ -3/2 \sin \phi t + 1/2 \cos \phi t \end{bmatrix}$

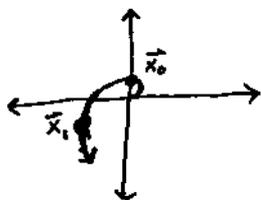
$x(t) = \sqrt{13}^t \begin{bmatrix} -3/2 \cos \phi t - 1/2 \sin \phi t - 3/2 \sin \phi t + 1/2 \cos \phi t \\ -3 \sin \phi t + \cos \phi t \end{bmatrix}$

$x(t) = (\sqrt{13})^t \begin{bmatrix} -5 \sin \phi t \\ \cos \phi t - 3 \sin \phi t \end{bmatrix} \quad \text{where } \phi \approx 2.16$

HW #19 (page 3)

22. (continued)

$$r = \sqrt{19} > 1 \Rightarrow \text{spirals out}$$



28. $\vec{x}(t+1) = (A - 2I_n)\vec{x}(t)$

Let λ be an eigen value of A

• $(\lambda - 2)$ is e-val of $(A - 2I_n)$

$$|\lambda - 2| > 1$$

\Rightarrow not stable

40. a. $A^T A = (p^2 + q^2 + r^2 + s^2)I_4$

f. Let $A = \begin{bmatrix} 3 & -3 & -4 & -5 \\ 3 & 3 & 5 & -4 \\ 4 & -5 & 3 & 3 \\ 5 & 4 & -3 & 3 \end{bmatrix}$ and $\vec{x} = \begin{bmatrix} 1 \\ 2 \\ 4 \\ 4 \end{bmatrix}$

then $A\vec{x} = \begin{bmatrix} -39 \\ 13 \\ 18 \\ 13 \end{bmatrix}$

$$39^2 + 13^2 + 18^2 + 13^2 = (3^2 + 3^2 + 4^2 + 5^2)(1^2 + 2^2 + 4^2 + 4^2) = 2183$$

9. Any positive integer can be expressed as $m = p_1 p_2 \dots p_n$ using part f repeatedly, we see that

$p_1, p_1 p_2, p_1 p_2 p_3, \dots, p_1 p_2 p_3 \dots p_{n-1}$, and finally m can be expressed as the sum of four squares.

42. a. $A = \begin{bmatrix} 1 & -k \\ k & 1-k^2 \end{bmatrix}$

b. $f_A(\lambda) = \lambda^2 - (2-k^2)\lambda + 1 = 0$

The discriminant is $(2-k^2)^2 - 4 = -4k^2 + k^4 = k^2(k^2 - 4)$ is negative if k is a small positive number. Therefore, the eigen values are complex and the trajectory will be an ellipse since $\det(A) = 1$.

HW #20

7.1/1, 3, 6, 8, 14, 21, 24, 28

$$1. \begin{bmatrix} 7 \\ 16 \end{bmatrix} = c_1 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + c_2 \begin{bmatrix} 5 \\ 12 \end{bmatrix}$$

$c_1 = -4, c_2 = 3$ is the solution, so

$\begin{bmatrix} -4 \\ 3 \end{bmatrix}$ is the desired coordinate vector

$$3. A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, S = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$$S^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

$$B = S^{-1}AS = \begin{bmatrix} -1 & -1 \\ 4 & 6 \end{bmatrix}$$

6. a. $\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}$ are in the plane.

$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is perpendicular to the plane.

$$B = \begin{bmatrix} \uparrow T(\vec{v}_1)_B & \uparrow T(\vec{v}_2)_B & \uparrow T(\vec{v}_3)_B \\ \downarrow & \downarrow & \downarrow \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

b. $A = SBS^{-1}$

$$= \begin{bmatrix} 1 & -1 & 1 \\ 1 & 2 & 2 \\ -1 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 2 & 2 \\ -1 & -1 & 3 \end{bmatrix}^{-1}$$

$$= \frac{1}{14} \begin{bmatrix} 12 & -4 & -6 \\ -4 & 6 & -12 \\ -6 & -12 & -4 \end{bmatrix}$$

$$8. B = \begin{bmatrix} 1 & 9 \\ 9 & 4 \end{bmatrix}, S = \begin{bmatrix} 3 & 5 \\ 5 & 8 \end{bmatrix}$$

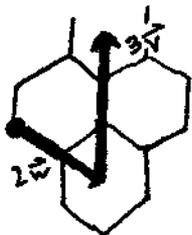
$$S^{-1} = \begin{bmatrix} -8 & 5 \\ 5 & -3 \end{bmatrix}$$

$$A = SBS^{-1} = \begin{bmatrix} -74 & 54 \\ -111 & 82 \end{bmatrix}$$

14. a. $\vec{OP} = \vec{w} + 2\vec{v}$
 $\Rightarrow [\vec{OP}]_{\mathcal{B}} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$\vec{OQ} = \vec{v} + 2\vec{w}$
 $\Rightarrow [\vec{OQ}]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

b. $\vec{OR} = 3\vec{v} + 2\vec{w}$



\rightarrow center of tile

c. observe that adding $3\vec{v}$ or $3\vec{w}$ to any vertex gives us another vertex.

Thus $17\vec{v} + 13\vec{w}$ is on a vertex iff $2\vec{v} + \vec{w}$ is on a vertex. From a) we know $2\vec{v} + \vec{w}$ is on a vertex.

so $5S$ is on a vertex.

21. $T(\vec{v}_1) = \vec{v}_1 \times \vec{v}_2 = \vec{v}_3$ so $T(\vec{v}_1)_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$T(\vec{v}_2) = \vec{v}_2 \times \vec{v}_2 = \vec{0}$ so $T(\vec{v}_2)_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

$T(\vec{v}_3) = \vec{v}_3 \times \vec{v}_2 = -\vec{v}_1$ so $T(\vec{v}_3)_{\mathcal{B}} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$

Thus $B = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$

$$24.a. \vec{v}_0 + \vec{v}_1 + \vec{v}_2 + \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$b. \vec{v}_0 + \vec{v}_1 + \vec{v}_2 + \vec{v}_3 = \vec{0} \quad (\text{from above})$$

$$\Rightarrow \vec{v}_0 = -\vec{v}_1 - \vec{v}_2 - \vec{v}_3$$

$$[\vec{v}_0]_{\mathcal{B}} = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$$

$$c. T(\vec{v}_2) = T(-\vec{v}_0 - \vec{v}_1 - \vec{v}_3) = -\vec{v}_3 - \vec{v}_0 - \vec{v}_1 = \vec{v}_2$$

Hence, T is 120° rotation around the line spanned by \vec{v}_2

$$B = \begin{bmatrix} T(\vec{v}_1)_{\mathcal{B}} & T(\vec{v}_2)_{\mathcal{B}} & T(\vec{v}_3)_{\mathcal{B}} \end{bmatrix}$$

~~matrix~~

$$B = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

$$f_B(\lambda) = \lambda^3 - 1, \text{ so } \lambda = 1, \frac{\pm \sqrt{3}}{2} i = \cos(120^\circ) \pm i \sin(120^\circ)$$

$B^3 = I_3$ since rotation by 120° three times returns a vector to its original position.

28. First, note that diagonal entries s_{ii} of S give the unit price of good i .

If a_{ij} tells us how many dollars' worth of good i are required to produce one dollar's worth of good j , then $a_{ij}s_{jj}$ tells us how many dollars' worth of good i are required to produce one unit

of good j , and $s_{ii}^{-1}a_{ij}s_{jj}$ is the number of units of good i required to produce one unit of good j . Thus $b_{ij} = s_{ii}^{-1}a_{ij}s_{jj}$, and

$$B = S^{-1}AS$$

$$B = \begin{bmatrix} .3 & .5 & .5 \\ .04 & .3 & .6 \\ .04 & .1 & .1 \end{bmatrix}$$

HW # 21

7.2 / 14, 15, 21, 22, ~~23~~, 35, 54, 60

$$14. f_{A(\lambda)} = \det \begin{bmatrix} \lambda+4 & -10 \\ 4 & \lambda-8 \end{bmatrix} = (\lambda+4)(\lambda-8) + 40 = \lambda^2 - 4\lambda + 8$$

$$\lambda = \frac{4 \pm \sqrt{16-32}}{2}$$

$$\lambda = 2 \pm 2i$$

$$E_{2+2i} = \ker \begin{bmatrix} 6+2i & -10 \\ 4 & -6+2i \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 6+2i & -10 & 0 \\ 4 & -6+2i & 0 \end{array} \right] \xrightarrow{+(6-2i)} \left[\begin{array}{cc|c} 40 & -6+20i & 0 \\ 4 & -6+2i & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 2 & -3-i & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$E_{2+2i} = \text{span} \begin{bmatrix} 3-i \\ 2 \end{bmatrix}$$

$$E_{2-2i} = \text{span} \begin{bmatrix} 3+i \\ 2 \end{bmatrix}$$

$$S = \begin{bmatrix} 3-i & 3+i \\ 2 & 2 \end{bmatrix}, \quad D = \begin{bmatrix} 2+2i & 0 \\ 0 & 2-2i \end{bmatrix}$$

$$S^{-1} \begin{bmatrix} -4 & 10 \\ -4 & 8 \end{bmatrix} S = D$$

15. $f_A(\lambda) = (\lambda+1)^2$, so $M = -A$ is a shear

Let \vec{w} be some vector, not an eigenvector for M .

Then $\{\vec{w} - M\vec{w}, \vec{w}\}$ gives us a basis for \mathbb{R}^2

with respect to this basis, the matrix for M is

$$\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

If we let $\vec{w} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ then $\vec{w} - M\vec{w} = \begin{bmatrix} 8 \\ -4 \end{bmatrix}$, so $S = \begin{bmatrix} 8 & 0 \\ -4 & 1 \end{bmatrix}$ and $S^{-1}MS = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$

Then $S^{-1}AS = S^{-1}(-M)S = \begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix}$, as required

HW #21 (page 2)

21. Yes.

$$\text{let } S = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\text{then } \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} = S^{-1} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} S$$

22. $A = \begin{bmatrix} -1 & 6 \\ -2 & 6 \end{bmatrix}$

$$f_A(\lambda) = (\lambda+1)(\lambda-6)+12 = \lambda^2 - 5\lambda + 6 = (\lambda-2)(\lambda-3)$$

$$\lambda = 2, 3$$

$$\Rightarrow A \text{ is similar to } D = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$

Yes

23. Yes. Both shears are similar to $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ (see example 6 in textbook), so they are also similar to one another

35. $M = \frac{1}{2} A$ is a shear,

so $M^t(\vec{x}_0) = \vec{x}_0 + t(M\vec{x}_0 - \vec{x}_0)$ (see example 7 in textbook)

$$= \begin{bmatrix} 0 \\ 1 \end{bmatrix} + t \left(\begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} -t/2 \\ 1-t/2 \end{bmatrix}$$

$$\vec{x}(t) = A^t \vec{x}_0 = 2^t M^t \vec{x}_0 = 2^t \begin{bmatrix} -t/2 \\ 1-t/2 \end{bmatrix} = 2^{t-1} \begin{bmatrix} -t \\ 2-t \end{bmatrix}$$

54. First, observe that $\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}^t = \begin{bmatrix} 1 & at \\ 0 & 1 \end{bmatrix}$

Proof: (by induction)

$$\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}^2 = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2a \\ 0 & 1 \end{bmatrix}$$

Next, if $\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}^{t-1} = \begin{bmatrix} 1 & (t-1)a \\ 0 & 1 \end{bmatrix}$ then

$$\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}^t = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}^{(t-1)} \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & (t-1)a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & ta \\ 0 & 1 \end{bmatrix}$$

(continued)

54. (continued)

$$\begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix}^t = \lambda^t \begin{bmatrix} 1 & \frac{1}{\lambda} \\ 0 & 1 \end{bmatrix}^t = \lambda^t \begin{bmatrix} 1 & \frac{t}{\lambda} \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \lambda^t & t\lambda^{t-1} \\ 0 & \lambda^t \end{bmatrix}$$

60. a. We are told that the dimension of the Eigenspace E_λ is d we choose a basis $\vec{v}_1, \dots, \vec{v}_d$ of E_λ and a basis $\vec{v}_{d+1}, \dots, \vec{v}_n$ of $(E_\lambda)^\perp$, then $\vec{v}_1, \dots, \vec{v}_n$ will be a basis of \mathbb{R}^n .

b. For $i = 1, \dots, d$, (ith ~~column~~ of B) = $T(\vec{v}_i)_B = \begin{bmatrix} 0 \\ \vdots \\ \lambda \\ \vdots \\ 0 \end{bmatrix}$ ← ith component.

so that $B = \left[\begin{array}{c|c} \lambda I_d & * \\ \hline 0 & * \end{array} \right]$

c. $f_B(\lambda) = \det \left[\begin{array}{c|c} (\lambda - \lambda_0) I_d & * \\ \hline 0 & * \end{array} \right] = (\lambda - \lambda_0)^d g(\lambda)$, so that

algebraic multiplicity of λ_0 as e-val of A = alg. mult of λ_0 as e-val of B
 $\geq d$
 $=$ geom. mult. of λ_0 as e-val of A .