

Homework 7.1 : 2, 4, 6, 12, 14, 24

2. To find  $a, b, c, d$  in 
$$\begin{bmatrix} -4 \\ 4 \\ 3 \\ -3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + b \begin{bmatrix} 5 \\ 6 \\ 7 \\ 8 \end{bmatrix} + c \begin{bmatrix} 2 \\ 3 \\ 5 \\ 7 \end{bmatrix} + d \begin{bmatrix} 1 \\ 9 \\ 9 \\ 4 \end{bmatrix}$$

we need to solve the system 
$$\begin{cases} a + 5b + 2c + d = -4 \\ 2a + 6b + 3c + 9d = 4 \\ 3a + 7b + 5c + 9d = 3 \\ 4a + 8b + 7c + 4d = -3 \end{cases}$$

$\Rightarrow a=2, b=-1, c=-1, d=1$

Then the coordinate vector of  $\begin{bmatrix} -4 \\ 4 \\ 3 \\ -3 \end{bmatrix}$  in this system is  $\begin{bmatrix} 2 \\ -1 \\ -1 \\ 1 \end{bmatrix}$

4. 
$$A = \begin{bmatrix} 7 & -1 \\ -6 & 8 \end{bmatrix} \quad S = \begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix} \quad S^{-1} = \frac{1}{5} \begin{bmatrix} 3 & 1 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 0.6 & 0.2 \\ -0.4 & 0.2 \end{bmatrix}$$
  

$$B = S^{-1}AS = \begin{bmatrix} 5 & 0 \\ 0 & 10 \end{bmatrix}$$

6a.  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is reflection in the plane  $x_1 + 2x_2 + 3x_3 = 0$ .

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}$$

Notice that  $\vec{v}_1$  and  $\vec{v}_2$  are both in the plane, while  $\vec{v}_3$  is normal to it. So  $T(\vec{v}_1) = \vec{v}_1, T(\vec{v}_2) = \vec{v}_2, T(\vec{v}_3) = -\vec{v}_3$ .

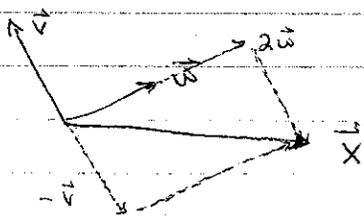
The matrix  $B$  of  $T$  relative to  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is 
$$\begin{bmatrix} [T(\vec{v}_1)]_{\beta} & [T(\vec{v}_2)]_{\beta} & [T(\vec{v}_3)]_{\beta} \\ \vdots & \vdots & \vdots \end{bmatrix}$$

so 
$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$



b. 
$$A = SBS^{-1} = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 2 & 2 \\ -1 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 2 & 3 \\ -1 & -1 & 3 \end{bmatrix}^{-1} = \frac{1}{14} \begin{bmatrix} 13 & -2 & -3 \\ -2 & 10 & -6 \\ -3 & -6 & 5 \end{bmatrix}$$

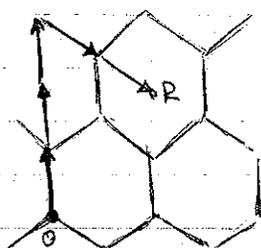
13.  $[\vec{x}]_{\beta} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$



$$\vec{x} = -\vec{v} + 2\vec{w}$$

14a.  $[\vec{OP}]_{\beta} \Rightarrow \vec{w} + 2\vec{v}$  so  $[\vec{OP}]_{\beta} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$   
 $[\vec{OQ}]_{\beta} \Rightarrow \vec{v} + 2\vec{w}$  so  $[\vec{OQ}]_{\beta} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$

b.



R is at the center of a tile.

c.  $[\vec{OS}]_{\beta} = \begin{bmatrix} 17 \\ 13 \end{bmatrix}$  If  $u$  is at a vertex,  $u + 3\vec{v}$  will be, as will  $u + 3\vec{w}$ . Notice  $17\vec{v} + 13\vec{w} = (2\vec{v} + \vec{w}) + 5(3\vec{v}) + 4(3\vec{w})$ .  
Therefore  $S$  is at a vertex.

24a.  $\vec{v}_0 + \vec{v}_1 + \vec{v}_2 + \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \vec{0}$

b.  $\vec{v}_0 = -\vec{v}_1 - \vec{v}_2 - \vec{v}_3$ , so if  $\beta = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ ,  $[\vec{v}_0]_{\beta} = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$

c.  $T(\vec{v}_0) = \vec{v}_3$ ,  $T(\vec{v}_3) = \vec{v}_1$ ,  $T(\vec{v}_1) = \vec{v}_0$ .

$$T(\vec{v}_2) = T(-\vec{v}_0 - \vec{v}_1 - \vec{v}_3) = -T(\vec{v}_0) - T(\vec{v}_1) - T(\vec{v}_3) = -\vec{v}_3 - \vec{v}_0 - \vec{v}_1 = \vec{v}_2$$

So  $T$  is a rotation by  $120^\circ$  about the line spanned by  $\vec{OP}_2$ .

$$B = \begin{bmatrix} [T(\vec{v}_1)]_{\beta} & [T(\vec{v}_2)]_{\beta} & [T(\vec{v}_3)]_{\beta} \\ [T(\vec{v}_0)]_{\beta} & [T(\vec{v}_1)]_{\beta} & [T(\vec{v}_2)]_{\beta} \\ [T(\vec{v}_2)]_{\beta} & [T(\vec{v}_3)]_{\beta} & [T(\vec{v}_0)]_{\beta} \end{bmatrix} = \begin{bmatrix} [\vec{v}_3]_{\beta} & [\vec{v}_2]_{\beta} & [\vec{v}_1]_{\beta} \\ [\vec{v}_0]_{\beta} & [\vec{v}_1]_{\beta} & [\vec{v}_2]_{\beta} \\ [\vec{v}_2]_{\beta} & [\vec{v}_3]_{\beta} & [\vec{v}_0]_{\beta} \end{bmatrix} = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

$$f_B(\lambda) = \lambda^3 - 1, \text{ so } \lambda_1 = 1, \lambda_{2,3} = -\frac{1}{2} \pm \frac{\sqrt{3}}{2}i = \text{cis}(\pm 120^\circ)$$

$B^3 = I_3$  and this makes sense since  $B$  is rotation by  $120^\circ$  and if you do this three times, you should get back to the start.