

$$5. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2)\vec{w}_1}{\text{length}} = \frac{1}{\sqrt{18}} \begin{bmatrix} -1 \\ -1 \\ 4 \end{bmatrix} = \frac{1}{3\sqrt{2}} \begin{bmatrix} -1 \\ -1 \\ 4 \end{bmatrix}$$

$$6. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \vec{e}_1$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2)\vec{w}_1}{\text{length}} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \vec{e}_2$$

$$\vec{w}_3 = \frac{\vec{v}_3 - (\vec{w}_1 \cdot \vec{v}_3)\vec{w}_1 - (\vec{w}_2 \cdot \vec{v}_3)\vec{w}_2}{\text{length}} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{e}_3$$

7. Note that \vec{v}_1 and \vec{v}_2 are orthogonal, so that $\vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$ and $\vec{w}_2 = \frac{1}{\|\vec{v}_2\|} \vec{v}_2 = \frac{1}{3} \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix}$. Then

$$\vec{w}_3 = \frac{\vec{v}_3 - (\vec{w}_1 \cdot \vec{v}_3)\vec{w}_1 - (\vec{w}_2 \cdot \vec{v}_3)\vec{w}_2}{\text{length}} = \frac{1}{\sqrt{36}} \begin{bmatrix} 2 \\ -4 \\ 4 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}.$$

$$8. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{7} \begin{bmatrix} 5 \\ 4 \\ 2 \\ 2 \end{bmatrix}$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2)\vec{w}_1}{\text{length}} = \frac{1}{7} \begin{bmatrix} -2 \\ 2 \\ 5 \\ -4 \end{bmatrix}$$

$$13. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2) \vec{w}_1}{\text{length}} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$\vec{w}_3 = \frac{\vec{v}_3 - (\vec{w}_1 \cdot \vec{v}_3) \vec{w}_1 - (\vec{w}_2 \cdot \vec{v}_3) \vec{w}_2}{\text{length}} = \begin{bmatrix} \frac{1}{2} \\ 1 \\ 2 \\ -\frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$$

$$14. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{10} \begin{bmatrix} 1 \\ 7 \\ 1 \\ 7 \end{bmatrix}$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2) \vec{w}_1}{\text{length}} = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\vec{w}_3 = \frac{\vec{v}_3 - (\vec{w}_1 \cdot \vec{v}_3) \vec{w}_1 - (\vec{w}_2 \cdot \vec{v}_3) \vec{w}_2}{\text{length}} = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

$$20. Q = I_3, R = [\vec{v}_1 \quad \vec{v}_2 \quad \vec{v}_3] = \begin{bmatrix} 2 & 3 & 5 \\ 0 & 4 & 6 \\ 0 & 0 & 7 \end{bmatrix}$$

$$21. Q = \frac{1}{3} \begin{bmatrix} 2 & -2 & 1 \\ 2 & 1 & -2 \\ 1 & 2 & 2 \end{bmatrix}, R = \begin{bmatrix} 3 & 0 & 12 \\ 0 & 3 & -12 \\ 0 & 0 & 6 \end{bmatrix}$$

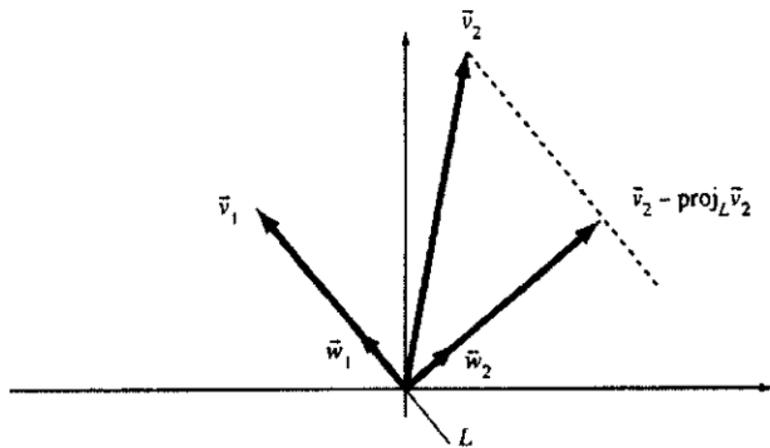
$$22. Q = \frac{1}{7} \begin{bmatrix} 5 & -2 \\ 4 & 2 \\ 2 & 5 \\ 2 & -4 \end{bmatrix}, R = \begin{bmatrix} 7 & 7 \\ 0 & 7 \end{bmatrix}$$

$$23. Q = \begin{bmatrix} 0.5 & -0.1 \\ 0.5 & 0.7 \\ 0.5 & -0.7 \\ 0.5 & 0.1 \end{bmatrix}, R = \begin{bmatrix} 2 & 4 \\ 0 & 10 \end{bmatrix}$$

$$28. Q = \begin{bmatrix} \frac{1}{10} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{7}{10} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{10} & \frac{1}{\sqrt{2}} & 0 \\ \frac{7}{10} & 0 & -\frac{1}{\sqrt{2}} \end{bmatrix}, R = \begin{bmatrix} 10 & 10 & 10 \\ 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \end{bmatrix}$$

$$29. \vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{5} \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$\vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2)\vec{w}_1}{\text{length}} = \frac{1}{5} \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$



$$34. \text{rref}(A) = \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

A basis of $\ker(A)$ is $\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix}$.

We apply the Gram-Schmidt process and obtain

$$\vec{w}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{w}_2 = \frac{\vec{v}_2 - (\vec{w}_1 \cdot \vec{v}_2)\vec{w}_1}{\text{length}} = \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -1 \\ -4 \\ 3 \end{bmatrix}$$

$$35. \text{rref}(A) = \begin{bmatrix} 1 & 0 & \frac{1}{3} \\ 0 & 1 & \frac{1}{3} \\ 0 & 0 & 0 \end{bmatrix}$$

The pivot columns of A give us a basis of $\text{im}(A)$:

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$$

Since \vec{v}_1 and \vec{v}_2 are orthogonal already, we obtain $\vec{w}_1 = \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$, $\vec{w}_2 = \frac{1}{3} \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$.