

## True or False

1. T, by Fact 7.2.2
2. T, by Definition 7.2.3
3. F; If  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ , then eigenvalue 1 has geometric multiplicity 1 and algebraic multiplicity 2.
4. T, by Fact 7.4.3
5. T;  $A = AI_n = A[\vec{e}_1 \dots \vec{e}_n] = [\lambda_1 \vec{e}_1 \dots \lambda_n \vec{e}_n]$  is diagonal.
6. T; If  $A\vec{v} = \lambda\vec{v}$ , then  $A^3\vec{v} = \lambda^3\vec{v}$ .
7. T; Consider a diagonal  $5 \times 5$  matrix with only two distinct diagonal entries.
8. F, by Fact 7.2.7.
9. T, by Summary 7.1.4
10. T, by Fact 7.2.4
11. F; Consider  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$
12. F; Let  $A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ ,  $\alpha = 2$ ,  $B = \begin{bmatrix} 4 & 0 \\ 0 & 5 \end{bmatrix}$ ,  $\beta = 5$ , for example. Then  $\alpha\beta = 10$  isn't an eigenvalue of  $AB = \begin{bmatrix} 8 & 0 \\ 0 & 15 \end{bmatrix}$ .
13. T; If  $A\vec{v} = 3\vec{v}$ , then  $A^2\vec{v} = 9\vec{v}$ .
14. T; Construct an eigenbasis by combining a basis of  $V$  with a basis of  $V^\perp$ .
15. T, by Fact 7.5.5
16. F; Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix}$ , for example.
17. T, by Example 6 of Section 7.5
18. T; The geometric multiplicity of eigenvalue 0 is  $\dim(\ker A) = n - \text{rank}(A)$ .

19. T; If  $S^{-1}AS = D$ , then  $S^T A^T (S^T)^{-1} = D$ .

20. F; Let  $A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ , for example.

21. F; Consider  $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ , with  $A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ .

22. T, by Fact 7.5.5

23. F; Let  $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ , for example.

24. F; Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$ , with  $AB = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}$ , for example.

25. T; If  $S^{-1}AS = D$ , then  $S^{-1}A^{-1}S = D^{-1}$  is diagonal

26. F; the equation  $\det(A) = \det(A^T)$  holds for all square matrices, by Fact 6.2.1

27. T; The sole eigenvalue, 7, must have geometric multiplicity 3.

28. F; Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$ , with  $A + B = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ , for example.

29. F; Consider the zero matrix.

30. T; If  $A\vec{v} = \alpha\vec{v}$  and  $B\vec{v} = \beta\vec{v}$ , then  $(A + B)\vec{v} = A\vec{v} + B\vec{v} = \alpha\vec{v} + \beta\vec{v} = (\alpha + \beta)\vec{v}$ .

31. F; Consider the identity matrix.

32. T; Both  $A$  and  $B$  are similar to  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ , by Fact 7.4.1

33. F; Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  and  $\vec{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , for example.

34. F; Consider  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$

35. F; Let  $A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ ,  $\vec{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , and  $\vec{w} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , for example.

36. T; A nonzero vector on  $L$  and a nonzero vector on  $L^\perp$  form an eigenbasis.

37. T; The eigenvalues are 3 and  $-2$ .

38. T, by Fact 7.3.7

39. T, by Fact 7.3.5

40. T; An eigenbasis for  $A$  is an eigenbasis for  $A + 4I_4$  as well.

41. F; Consider a rotation through  $\pi/2$ .

42. T; Suppose  $\begin{bmatrix} A & A \\ 0 & A \end{bmatrix} \begin{bmatrix} \vec{v} \\ \vec{w} \end{bmatrix} = \begin{bmatrix} A(\vec{v} + \vec{w}) \\ A\vec{w} \end{bmatrix} = \begin{bmatrix} \lambda\vec{v} \\ \lambda\vec{w} \end{bmatrix}$  for a nonzero vector  $\begin{bmatrix} \vec{v} \\ \vec{w} \end{bmatrix}$ . If  $\vec{w}$  is nonzero, then it is an eigenvector of  $A$  with eigenvalue  $\lambda$ ; otherwise  $\vec{v}$  is such an eigenvector.

43. F; Consider  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  and  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ .

44. T; Note that  $S^{-1}AS = D$ , so that  $D^4 = S^{-1}A^4S = S^{-1}0S = 0$ , and therefore  $D = 0$  (since  $D$  is diagonal) and  $A = SDS^{-1} = 0$ .

45. T; There is an eigenbasis  $\vec{v}_1, \dots, \vec{v}_n$ , and we can write  $\vec{v} = c_1\vec{v}_1 + \dots + c_n\vec{v}_n$ . The vectors  $c_i\vec{v}_i$  are either eigenvectors or zero.

46. T; If  $A\vec{v} = \alpha\vec{v}$  and  $B\vec{v} = \beta\vec{v}$ , then  $AB\vec{v} = \alpha\beta\vec{v}$ .

47. T, by Fact 7.3.8

48. F; Let  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ , for example.

49. T; Recall that the rank is the dimension of the image. If  $\vec{v}$  is in the image of  $A$ , then  $A\vec{v}$  is in the image of  $A$  as well, so that  $A\vec{v}$  is parallel to  $\vec{v}$ .

50. F; Consider  $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ .

51. T; If  $A\vec{v} = \lambda\vec{v}$  for a nonzero  $\vec{v}$ , then  $A^4\vec{v} = \lambda^4\vec{v} = \vec{0}$ , so that  $\lambda^4 = 0$  and  $\lambda = 0$ .

52. F; Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$ , for example.

53. T; If the eigenvalue associated with  $\vec{v}$  is  $\lambda = 0$ , then  $A\vec{v} = \vec{0}$ , so that  $\vec{v}$  is in the kernel of  $A$ ; otherwise  $\vec{v} = A\left(\frac{1}{\lambda}\vec{v}\right)$ , so that  $\vec{v}$  is in the image of  $A$ .

54. T; either there are two distinct real eigenvalues, or the matrix is of the form  $kI_2$ .

55. T; Either  $A\vec{u} = 3\vec{u}$  or  $A\vec{u} = 4\vec{u}$ .

56. T; Note that  $(\vec{u}\vec{u}^T)\vec{u} = \|\vec{u}\|^2\vec{u}$ .

57. T; Suppose  $A\vec{v}_i = \alpha_i\vec{v}_i$  and  $B\vec{v}_i = \beta_i\vec{v}_i$ , and let  $S = [\vec{v}_1 \dots \vec{v}_n]$ . Then  $ABS = BAS = [\alpha_1\beta_1\vec{v}_1 \dots \alpha_n\beta_n\vec{v}_n]$ , so that  $AB = BA$ .

58. T; Note that a nonzero vector  $\vec{v} = \begin{bmatrix} p \\ q \end{bmatrix}$  is an eigenvector of  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  if (and only if)  $A\vec{v} = \begin{bmatrix} ap + bq \\ cp + dq \end{bmatrix}$  is parallel to  $\vec{v} = \begin{bmatrix} p \\ q \end{bmatrix}$ , that is, if  $\det \begin{bmatrix} p & ap + bq \\ q & cp + dq \end{bmatrix} = 0$ . Check that this is the case if (and only if)  $\vec{v}$  is an eigenvector of  $\text{adj}(A)$  (use the same criterion).