

SOLVE SYSTEM:

$$\left. \begin{aligned} \frac{dx_1}{dt} &= 2x_1 & -4x_4 + 3x_5 \\ \frac{dx_2}{dt} &= & 2x_2 - 2x_3 + 2x_4 \\ \frac{dx_3}{dt} &= & x_2 & -x_4 \\ \frac{dx_4}{dt} &= & & -x_4 \\ \frac{dx_5}{dt} &= & & -3x_4 + 2x_5 \end{aligned} \right\}$$

$$\frac{d\vec{x}}{dt} = A\vec{x}$$

$$A = \begin{bmatrix} 2 & 0 & 0 & -4 & 3 \\ 0 & 2 & -2 & 2 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -3 & 2 \end{bmatrix}$$

Eigenvalues:

$$\lambda I - A = \begin{bmatrix} \lambda - 2 & 0 & 0 & 4 & -3 \\ 0 & \lambda - 2 & 2 & -2 & 0 \\ 0 & -1 & \lambda & 1 & 0 \\ 0 & 0 & 0 & \lambda + 1 & 0 \\ 0 & 0 & 0 & 3 & \lambda - 2 \end{bmatrix}$$

use Laplace expansion for determinant using rows with all but one zero.
 $\det(\lambda I - A)$
 $= (\lambda - 2)[(\lambda - 2)(\lambda + 1)(\lambda^2 - 2\lambda + 2)]$

$$= (\lambda - 2)^2 (\lambda + 1)(\lambda^2 - 2\lambda + 2) = 0$$

evaluate $\lambda_1 = \lambda_2 = 2$ $\lambda_3 = -1$ $\lambda_{4,5} = \frac{2 \pm \sqrt{4 - 8}}{2}$

$\Rightarrow \lambda_4 = 1 + i$ $\lambda_5 = \bar{\lambda}_4 = 1 - i$

$$\lambda_1 = \lambda_2 = 2 \Rightarrow \left[\begin{array}{ccccc|c} 0 & 0 & 0 & 4 & -3 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{ccccc|c} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Geom. mult = 1 < 2 = Alg. mult.

CANNOT FIND ANOTHER INDEP. E-VECTOR, BUT we can find a 2nd vector \vec{v}_2 such that $A\vec{v}_2 = \vec{v}_1 + \lambda\vec{v}_2$.

$$\Rightarrow \lambda\vec{v}_2 - A\vec{v}_2 = -\vec{v}_1 \Rightarrow (\lambda I - A)\vec{v}_2 = -\vec{v}_1 \quad (\text{with } \lambda = 2)$$

$$\Rightarrow \left[\begin{array}{ccccc|c} 0 & 0 & 0 & 4 & -3 & -1 \\ 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccccc|c} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1/3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{bmatrix} t \\ 0 \\ 0 \\ 0 \\ 1/3 \end{bmatrix}$$

For simplicity, choose $t = 0$
 $\Rightarrow \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1/3 \end{bmatrix}$

$$\lambda_3 = -1 \Rightarrow \left[\begin{array}{ccccc|c} -3 & 0 & 0 & 4 & -3 & 0 \\ 0 & -3 & 2 & -2 & 0 & 0 \\ 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & -3 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & -1/3 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

pick $x_5 = 3$
 $\Rightarrow \vec{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 3 \\ 3 \\ 3 \end{bmatrix}$

$$\lambda_4 = 1+i \Rightarrow \begin{bmatrix} -1+i & 0 & 0 & 4 & -3 \\ 0 & -1+i & 2 & -2 & 0 \\ 0 & -1 & 1+i & 1 & 0 \\ 0 & 0 & 0 & 2+i & 0 \\ 0 & 0 & 0 & 3 & -1+i \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} -1+i & 0 & 0 & 4 & -3 \\ 0 & -1+i & 2 & -2 & 0 \\ 0 & -1 & 1+i & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 3 & -1+i \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} -1+i & 0 & 0 & 0 & -3 \\ 0 & -1+i & 2 & 0 & 0 \\ 0 & -1 & 1+i & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & -1+i & 2 & 0 & 0 \\ 0 & -1 & 1+i & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{If } \vec{v} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \\ \delta \\ \epsilon \end{bmatrix} \text{ is complex eigenvector}$$

then $\alpha=0, \delta=0, \epsilon=0$ $(-1+i)\beta + 2\gamma = 0$
 or $-\beta + (1+i)\gamma = 0$ (easier)

$\Rightarrow \beta = (1+i)\gamma$ pick $\gamma=1 \Rightarrow \beta = 1+i$

$$\vec{v} = \begin{bmatrix} 0 \\ 1+i \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \vec{x} + i\vec{y} \quad \text{choose } \vec{v}_4 = \vec{y} \\ \vec{v}_5 = \vec{x}$$

CHANGE OF BASIS MATRIX is $S = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 & \vec{v}_5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 3 & 0 & 1 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 1/3 & 3 & 0 & 0 \end{bmatrix}$

This gives $S^{-1}AS = [A]_B = \begin{bmatrix} 2 & 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$

$$B = \{ \vec{v}_1, \dots, \vec{v}_5 \}$$

$$B =$$

$$\begin{cases} \frac{du_1}{dt} = 2u_1 + u_2 \\ \frac{du_2}{dt} = 2u_2 \\ \frac{du_3}{dt} = -u_3 \\ \frac{du_4}{dt} = u_4 - u_5 \\ \frac{du_5}{dt} = u_4 + u_5 \end{cases}$$

We've solved each of these cases individually

$$\vec{u}(t) = [e^{tB}] \vec{u}(0) \text{ where}$$

$$e^{tB} = \begin{bmatrix} e^{2t} & te^{2t} & 0 & 0 & 0 \\ 0 & e^{2t} & 0 & 0 & 0 \\ \hline 0 & 0 & e^{-t} & 0 & 0 \\ 0 & 0 & 0 & e^t \cos t & -e^t \sin t \\ 0 & 0 & 0 & e^t \sin t & e^t \cos t \end{bmatrix}$$

FINALLY, $A = SBS^{-1} \Rightarrow [e^{tA}] = S[e^{tB}]S^{-1}$

so $\vec{x}(t) = [e^{tA}] \vec{x}(0)$

$= S e^{tB} \underbrace{S^{-1} \vec{x}(0)}_{\begin{bmatrix} c_1 \\ \vdots \\ c_5 \end{bmatrix}} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 3 & 0 & 1 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 1/3 & 3 & 0 & 0 \end{bmatrix} \begin{bmatrix} e^{2t} & te^{2t} & 0 & 0 & 0 \\ 0 & e^{2t} & 0 & 0 & 0 \\ 0 & 0 & e^{-t} & 0 & 0 \\ 0 & 0 & 0 & e^{t \sin t} & -e^{t \cos t} \\ 0 & 0 & 0 & e^{t \sin t} & e^{t \cos t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{bmatrix}$

$= \begin{bmatrix} e^{2t} & te^{2t} & e^{-t} & 0 & 0 \\ 0 & 0 & 0 & e^{t \cos t} + e^{t \sin t} & -e^{t \sin t} + e^{t \cos t} \\ 0 & 0 & 3e^{-t} & e^{t \sin t} & e^{t \cos t} \\ 0 & 0 & 3e^{-t} & 0 & 0 \\ 0 & 1/3 e^{2t} & 3e^{-t} & 0 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{bmatrix}$

$\Rightarrow \left\{ \begin{aligned} x_1(t) &= c_1 e^{2t} + c_2 t e^{2t} + c_3 e^{-t} \\ x_2(t) &= c_4 (e^{t \cos t} + e^{t \sin t}) + c_5 (-e^{t \sin t} + e^{t \cos t}) \\ x_3(t) &= 3c_3 e^{-t} + c_4 e^{t \sin t} + c_5 e^{t \cos t} \\ x_4(t) &= 3c_3 e^{-t} \\ x_5(t) &= \frac{1}{3} c_2 e^{2t} + 3c_3 e^{-t} \end{aligned} \right. \left. \begin{array}{l} \text{General} \\ \text{Solution} \\ \text{(PART A)} \end{array} \right\}$

In particular, if $\vec{x}(0) = \begin{bmatrix} 5 \\ 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$, then $\begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{bmatrix} = S^{-1} \vec{x}(0)$

$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1/3 & 0 \\ 0 & 0 & 0 & -3 & 3 \\ 0 & 0 & 0 & 1/3 & 0 \\ 0 & 1 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 13/3 \\ -3 \\ 2/3 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{bmatrix} \Rightarrow \begin{array}{l} x_1(t) = \frac{13}{3} e^{2t} - 3t e^{2t} + \frac{2}{3} e^{-t} \\ x_2(t) = e^t (4 \cos t + 2 \sin t) \\ x_3(t) = 2e^{-t} + e^t (3 \sin t + \cos t) \\ x_4(t) = 2e^{-t} \\ x_5(t) = -e^{2t} + 2e^{-t} \end{array}$

(PART b)