

Let  $\Sigma', \Sigma''$  be two smooth submanifolds in  $\mathbb{R}^{n'}$  and  $\mathbb{R}^{n''}$  and  $f : \Sigma' \rightarrow \Sigma''$  a map.

1. a) What does it mean that  $f$  is smooth.

b) Explain how to define the "natural" map  $f^* : \tilde{\Omega}^r(\Sigma'') \rightarrow \tilde{\Omega}^r(\Sigma')$  for any smooth map  $f : \Sigma' \rightarrow \Sigma''$ .

Let  $\Sigma \subset \mathbb{R}^n$  be a smooth  $d$ -dimensional manifold.

2.a) Show that for any  $\omega' \in \tilde{\Omega}^{r'}(\Sigma), \omega'' \in \tilde{\Omega}^{r''}(\Sigma)$  there exists a smooth  $r' + r''$ -form  $\omega \in \tilde{\Omega}^{r'+r''}(\Sigma), r = r' + r''$  such that for any  $\sigma \in \Sigma$  we have  $\omega'(\sigma) \wedge \omega''(\sigma) = \omega(\sigma)$ .

We denote the form  $\omega \in \tilde{\Omega}^r(\Sigma)$  by  $\omega' \wedge \omega''$ .

b) Show that  $\omega' \wedge \omega'' = (-1)^{r'r''} \omega'' \wedge \omega'$ .

Let  $V$  be a vector space of dimension  $n$  and  $e_1, \dots, e_n$  a basis of  $V$  and  $e^1, \dots, e^n$  be the dual basis. We denote by  $x_i, 1 \leq i \leq n$  linear functions on  $V$  given by  $x_i(v) := e_i(v)$ .

As in the problem set 2 we denote by  $\mathcal{A}(r, n)$  be the set of subsets  $I$  of  $[1, \dots, n]$  such that  $|I| = r$ . For any  $I = \{i_1 < \dots < i_r\} \in \mathcal{A}(r, n)$  we associate an  $r$ -linear form  $\omega^I$  on  $V$  by

$$\omega^I(v_1, \dots, v_r) := \sum_{\sigma \in S_r} \text{sign}(\sigma) \prod_{1 \leq k \leq r} e^{i_{\sigma(k)}}(v_k)$$

3. Show that for any  $I = \{i_1 < \dots < i_r\} \in \mathcal{A}(r, n), v \in V$  we have  $dx_{i_1} \wedge \dots \wedge dx_{i_r}(v) = \omega^I$

As you know [see the problem set 2] the set  $\omega^I, I \in \mathcal{A}(r, n)$  is a basis of the space  $\Omega^r(V)$ . Therefore for any open set  $U \subset \mathbb{R}^n$  and any differential form  $\omega \in \tilde{\Omega}^r(U)$  we can write  $\omega$  as a sum

$$\omega = \sum_{I=\{i_1 < \dots < i_r\} \in \mathcal{A}(r, n)} f_I dx_{i_1} \wedge \dots \wedge dx_{i_r}$$

where  $f_I, I \in \mathcal{A}(r, n)$  are smooth functions on  $U$ .

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be a smooth function,  $a \in \mathbb{R}, \Sigma_a := f^{-1}(a) \subset \mathbb{R}^n$ . Assume that for any  $\sigma \in \Sigma_a$  the map  $d(f)(\sigma) : \mathbb{R}^n \rightarrow \mathbb{R}$  is onto. [From now on I'll write  $df$  instead of  $Df$ ]. Then, as you know,  $\Sigma_a$  is a smooth submanifold of  $\mathbb{R}^n$  of dimension  $n - 1$ . Let  $\eta$  be the  $n$ -form on  $\mathbb{R}^n$ .

4. a) Show that for any  $\sigma \in \Sigma_a$  there exists an open neighbourhood  $U$  of  $\sigma$  in  $\mathbb{R}^n$  and  $n - 1$ -form  $\tilde{\omega}$  on  $U$  such that the restriction of  $\eta$  on  $U$  is equal to the product  $\tilde{\omega} \wedge df$ . [In other words, for any  $u \in U$  we have  $\tilde{\omega}(u) \wedge df(u) = \eta(u)$ ].

b) Show that the restriction  $\omega_a(\eta)$  of the form  $\tilde{\omega}$  on  $\Sigma_a \cap U$  does not depend on a choice of the form  $\tilde{\omega}$ . We denote this  $n - 1$ -form on  $\Sigma_a \cap U$  by  $\omega_a(\eta)|_U$ .

As follows from b), for any point  $\sigma \in \Sigma_a$  we have defined an element  $\omega_a(\eta)(\sigma)$  in  $\Omega^{n-1}(T_{\Sigma_a}(\sigma))$ .

c) Show the map  $\sigma \rightarrow \omega_a(\eta)(\sigma)$  is a smooth  $n - 1$ -form on  $\Sigma_a$ . We denote it by  $\omega_a(\eta)$ .

d) Show that for any  $a \in \mathbb{R}$  the  $n - 1$ -form  $\omega_a(dx^1 \wedge \dots \wedge dx^n)$  defines an orientation on  $\Sigma_a$ . We denote this orientation as  $\mathcal{O}_a$ .

e) Let  $\eta$  be an  $n$ -form on  $\mathbb{R}^n$  with compact support,  $\mathcal{O}$  be the standard orientation on  $\mathbb{R}^n$  [the one corresponding to the form  $dx^1 \wedge \dots \wedge dx^n$ ]. Show that  $\int_{\mathbb{R}^n} \eta = \int_{\mathbb{R}} f(a) da$  where  $f(a) := \int_{\Sigma_a}^{\mathcal{O}_a} \omega_a(\eta)$ .

f) Compute the form  $\omega := \omega_1(\eta)$  in the case when  $n = 3$ ,  $\eta(v) := e^1 \wedge e^2 \wedge e^3$  and  $f(x, y, z) = x^2 + y^2 + z^2$ . [Choose some system of local coordinates on  $\Sigma_1 = S^2$ .

g) Show that for any rotation  $f : S^2 \rightarrow S^2$  we have  $f^*(\omega_1) = \omega_1$ .

h) Choose an orientation on  $S^2$  and compute  $\int_{S^2}^{\mathcal{O}} \omega$ .

5. Do the problems 6.5.5; 6.5.13; 6.6.2; 6.9.3 and 6.9.7