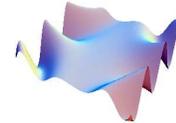


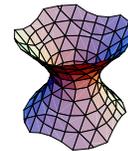
SCALAR FUNCTION (1D). ( $n = 1, m = 1$ ). A function of one variable, where each  $f(x)$  is a real number. The graph is a curve in the  $x, y$  plane. The derivative is  $f'(x)$ .



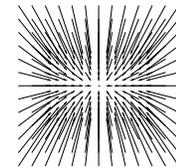
SCALAR FUNCTION (2D). ( $n = 2, m = 1$ ). A function  $f(x, y)$  defined in the plane is also called a scalar field. The graph of  $f$  is a curve in space (see figure). Level curves are curves in the plane. A derivative is  $\nabla f(x, y)$ , the gradient.



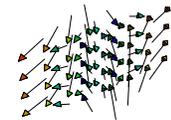
SCALAR FUNCTION (3D). ( $n = 3, m = 1$ ). A function  $f(x, y, z)$  defined in space is also called a scalar field. Its graph would be an object in 4D. Level surfaces are surfaces in space (see figure). A derivative is the gradient  $\nabla f(x, y, z)$ .



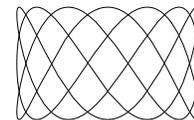
VECTOR FIELD (2D). ( $n = 2, m = 2$ ) A function on the plane which attaches a vector  $(P(x, y), Q(x, y))$  to each point  $(x, y)$ . Derivatives are  $\text{curl}(F) = Q_x - P_y$  or  $\text{div}(F) = P_x + Q_y$  both scalar fields (real valued functions). Also **coordinate changes**  $T(u, v) = (x(u, v), y(u, v))$  are the same mathematical object.



VECTOR FIELD (3D). ( $n = 3, m = 3$ ) At each point in space, we attach a vector  $F(x, y, z) = (P(x, y, z), Q(x, y, z), R(x, y, z))$  at each point  $(x, y, z)$ . Derivatives are the curl  $\text{curl}(F)$ , a vector field or the divergence  $\text{div}(F) = P_x + Q_y + R_z$ , a scalar field (real valued functions). Also **coordinate changes**  $T(u, v, w) = (x(u, v, w), y(u, v, w), z(u, v, w))$  are the same mathematical object.



CURVE (2D). ( $n = 1, m = 2$ ) For each  $t$  is defined a point  $r(t) = (x(t), y(t))$  in the plane. A derivative is  $r'(t) = (x'(t), y'(t))$ , the velocity.



CURVE (3D). ( $n = 1, m = 3$ ) For each  $t$ , we have a point  $r(t) = (x(t), y(t), z(t))$  in space. A derivative is  $r'(t) = (x'(t), y'(t), z'(t))$ , the velocity.



SURFACE (2D). ( $n = 2, m = 3$ ) For each  $(u, v)$  there is a point  $r(u, v) = (x(u, v), y(u, v), z(u, v))$  in space. The normal vector at a point  $r(u, v)$  is  $r_u(u, v) \times r_v(u, v)$ .

