

Unit 24

Divergence theorem

Theorem $\iiint_E \operatorname{div}(\vec{F}) dV = \iint_S \vec{F} \cdot d\vec{S}$

↑
triple integral

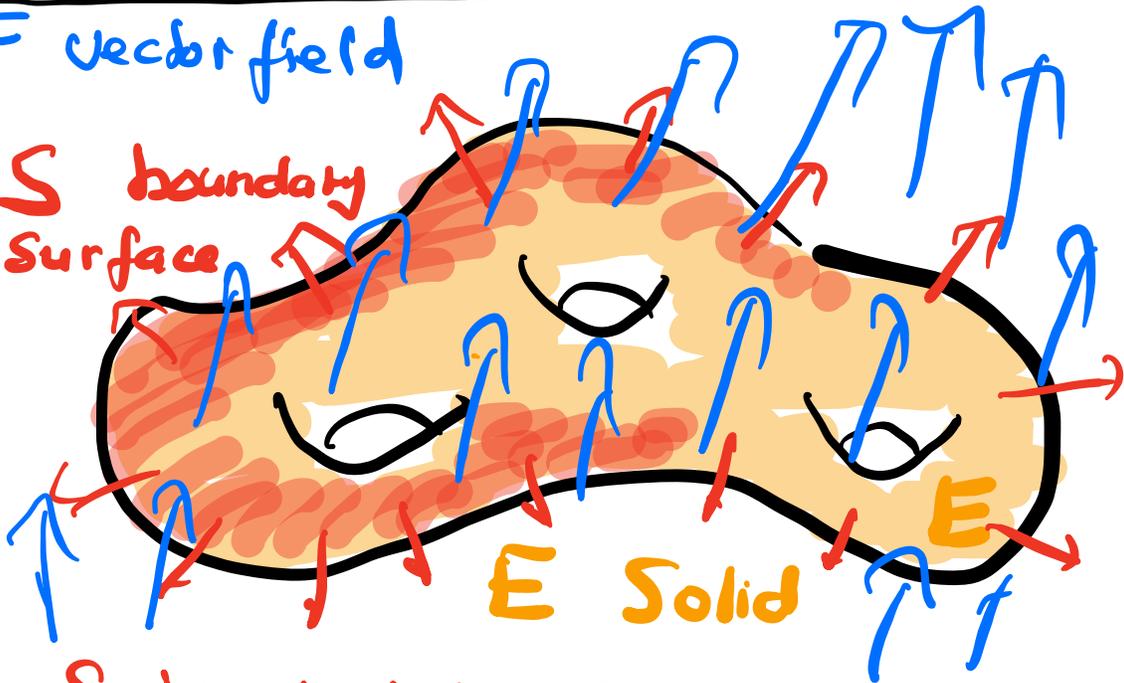
↑
flux integral

LHS: How much Field is generated inside

RHS: How much field leaves the surface

\vec{F} vector field

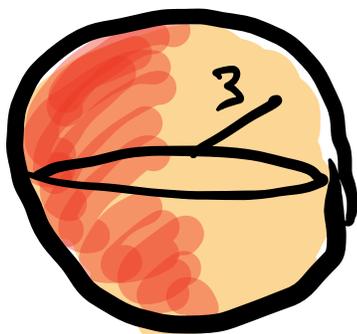
S boundary surface



S is oriented outwards

②

Example



$$E: x^2 + y^2 + z^2 \leq 9$$

Solid ball of radius 3

$$S: x^2 + y^2 + z^2 = 9$$

Sphere of radius 3

$$\vec{F} = \begin{bmatrix} 0 \\ 1 \\ z \end{bmatrix} = \begin{bmatrix} P \\ Q \\ R \end{bmatrix}$$

First: LHS of the theorem

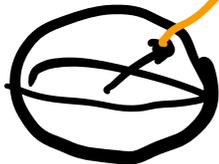
$$\operatorname{div}(\vec{F}) = P_x + Q_y + R_z = 1$$

$$\begin{aligned} \iiint_E \operatorname{div}(\vec{F}) \, dV &= \iiint_E 1 \, dV \\ &= \text{Volume of } (E) = \\ &= \frac{4\pi}{3} 3^3 = \boxed{36\pi} \end{aligned}$$

Second: RHS of the theorem

$$\vec{F}(\rho, \theta) = 3 \begin{bmatrix} \sin \rho \cos \theta \\ \sin \rho \sin \theta \\ \cos \rho \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \begin{matrix} 0 \leq \rho \leq \pi \\ 0 \leq \theta < 2\pi \end{matrix}$$

$$\vec{r}_\rho \times \vec{r}_\theta = 9 \sin \rho \begin{bmatrix} \sin \rho \cos \theta \\ \sin \rho \sin \theta \\ \cos \rho \end{bmatrix}$$



$$\int_0^{2\pi} \int_0^\pi \begin{bmatrix} 0 \\ 0 \\ 3 \cos \rho \end{bmatrix} \cdot \begin{bmatrix} 9 \sin^2 \rho \cos \theta \\ 9 \sin^2 \rho \sin \theta \\ 9 \sin \rho \cos \rho \end{bmatrix} d\rho d\theta$$

$$\int_0^{2\pi} \int_0^\pi 9 \sin^2 \rho \sin \theta + 27 \sin \rho \cos^2 \rho \, d\rho d\theta$$

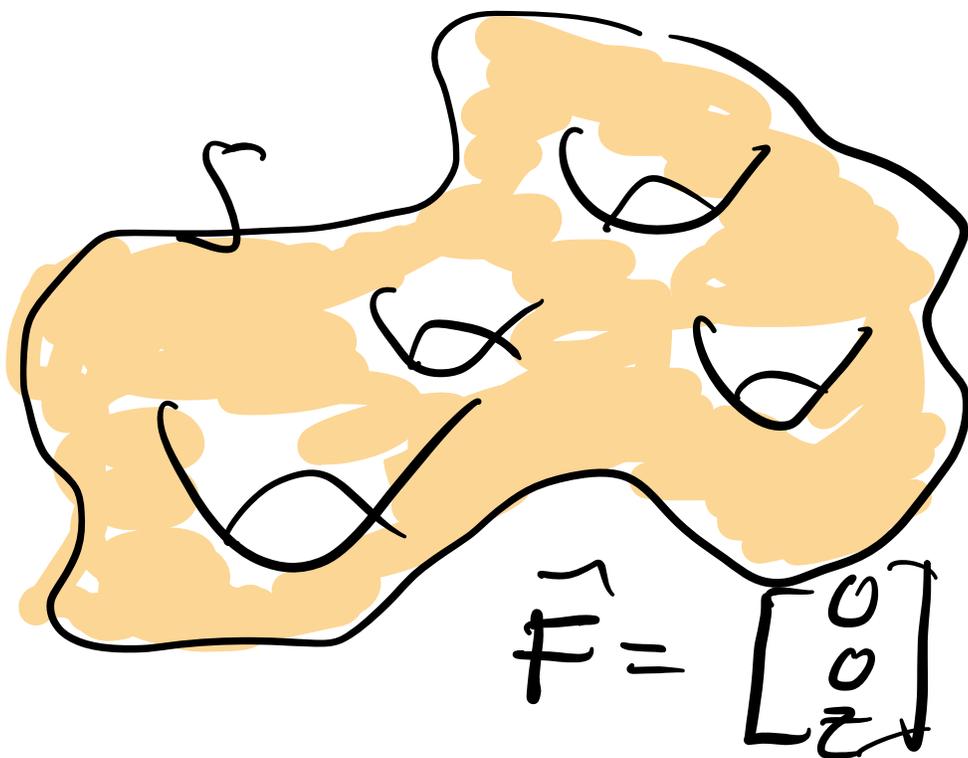
$\frac{1 - \cos 2\rho}{2}$

$$\int_0^{2\pi} \left[\frac{9}{2} \sin \theta - 27 \frac{\cos^3 \rho}{3} \right] \Big|_0^\pi d\theta$$

$$= \int_0^{2\pi} \left[\frac{9}{2} \cos \theta \Big|_0^{2\pi} - 27 \left(\frac{\cos^3(\pi) - \cos^3(0)}{3} \right) \right] d\theta$$

$$= \int_0^{2\pi} \frac{27 \cdot 2}{2} d\theta = \boxed{36\pi}$$

The triple integral was easier.



$\iint_S \vec{F} \cdot d\vec{s}$ is the volume of E

The boundary determines the volume

$$\vec{F} = \begin{bmatrix} 0 \\ 0 \\ z \end{bmatrix} \quad \text{div } \vec{F} = 1$$

$$\vec{F} = \begin{bmatrix} 0 \\ x \\ - \end{bmatrix} \quad \text{curl}(\vec{F}) = 1$$

③

Remarks

(A)

What happens
if $\vec{F} = \text{curl}(\vec{G})$

$$\iiint_{\vec{F}} \text{div} \text{curl}(\vec{G}) dV = \iint_{\vec{F}} \text{curl}(\vec{G}) d\vec{S}$$

why is $\vec{\text{curl}}(\vec{F})$ zero.

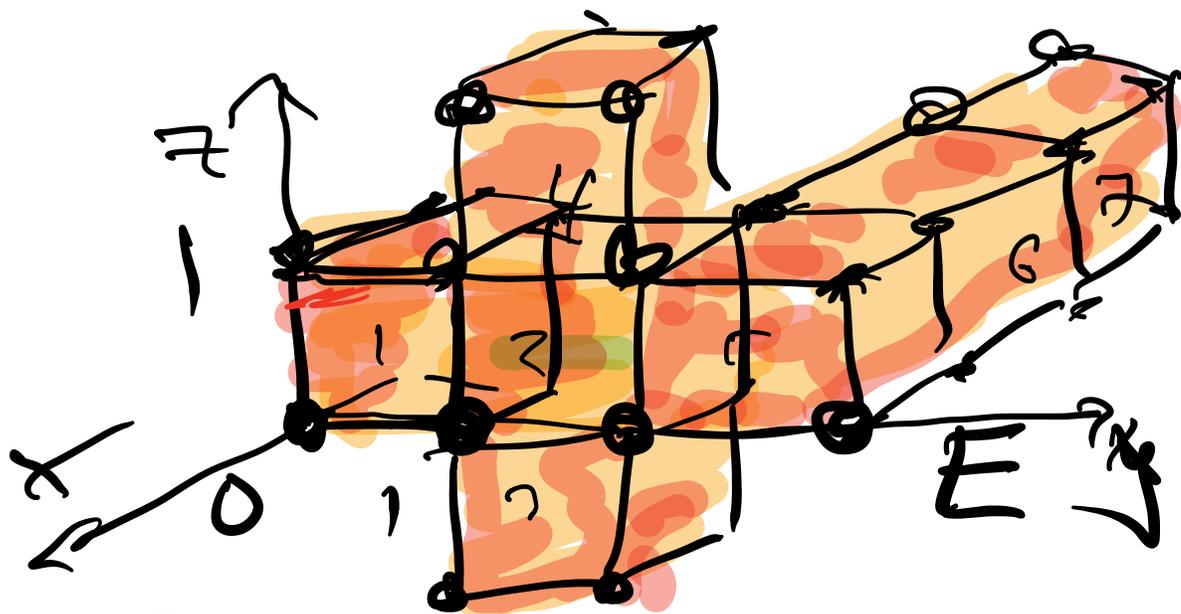
The flux of $\text{curl}(\vec{F})$ through a closed surface S is always zero.

We have seen that using Stokes theorem.

(B)

What happens if $\text{div}(\vec{F}) = c$ is constant?

Then the flux is equal to c times the volume.



$$\vec{F} = \begin{bmatrix} \sin zy + 3x \\ \sin \sin x \\ e^{yx} + 17z \end{bmatrix}$$

What is the flux of \vec{F} through S , bounding E oriented outwards

we use the divergence theorem:

$$\operatorname{div}(\vec{F}) = 20$$

$$7 \cdot 20 =$$

$$\iiint \operatorname{div}(\vec{F}) dV = \iiint 20 dV$$

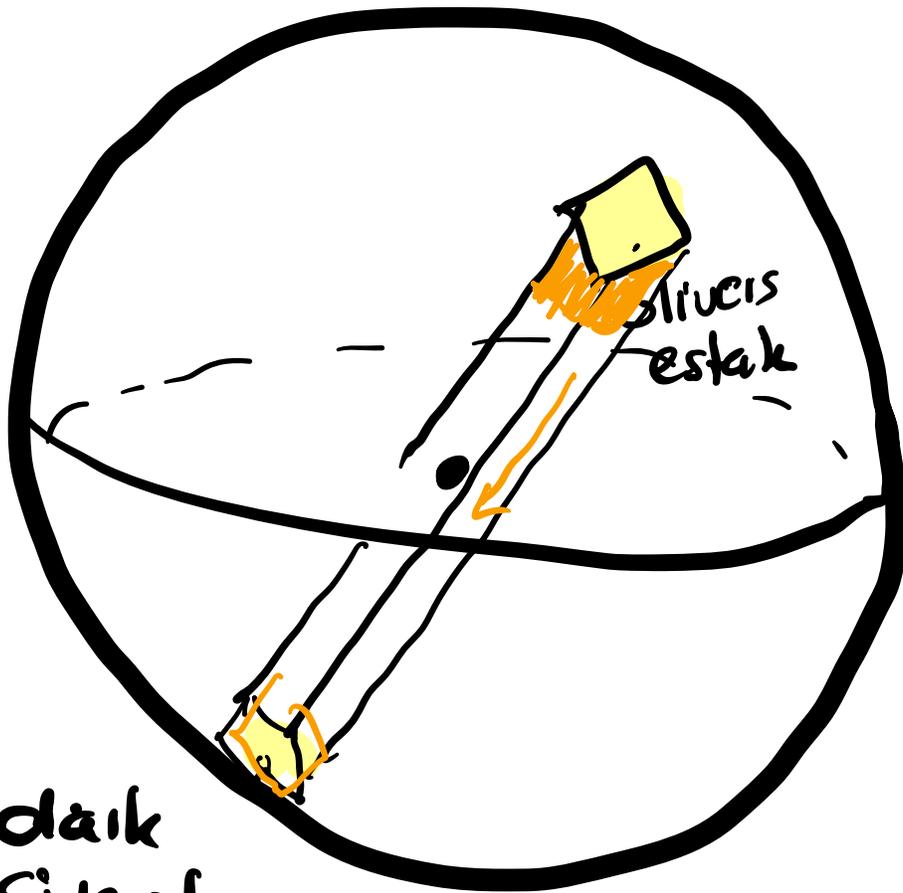
$$\equiv \boxed{140}$$

E

W
E

(4)

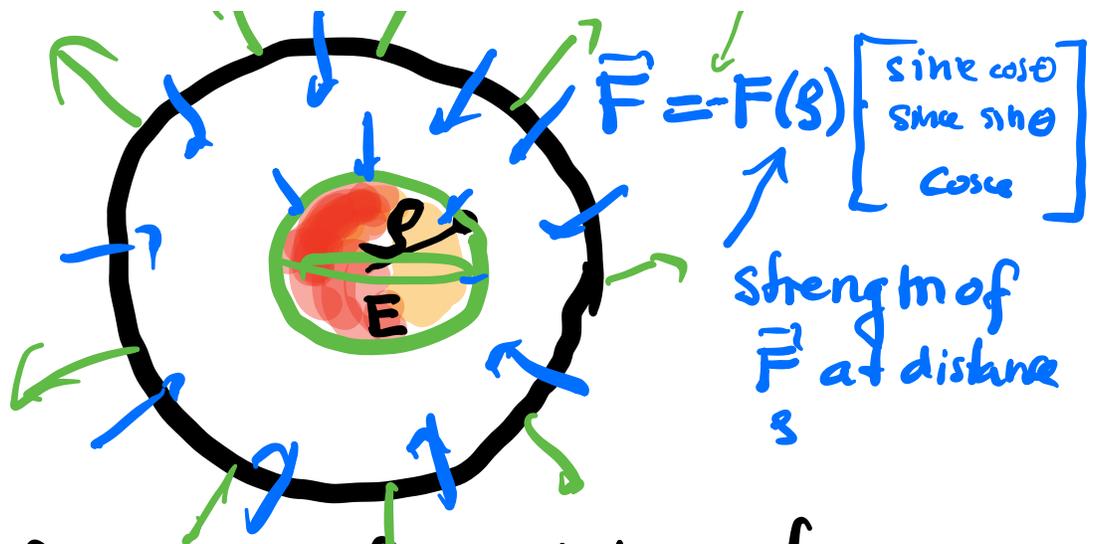
Moon plans



dark
side of
the moon

what is the
gravity at radius
 r inside the moon





Gauss reformulation of gravity as follows:

$$\text{div}(\vec{F}) = 4\pi\sigma$$

Use the divergence theorem: mass density

$$\iiint_E \text{div} \vec{F} \, dV = \iiint_E 4\pi\sigma \, dV$$

||

$$\iint \vec{F} \cdot d\vec{S}$$

$$= 4\pi \cdot \left(\frac{4\pi}{3} \rho s^3 \right)$$

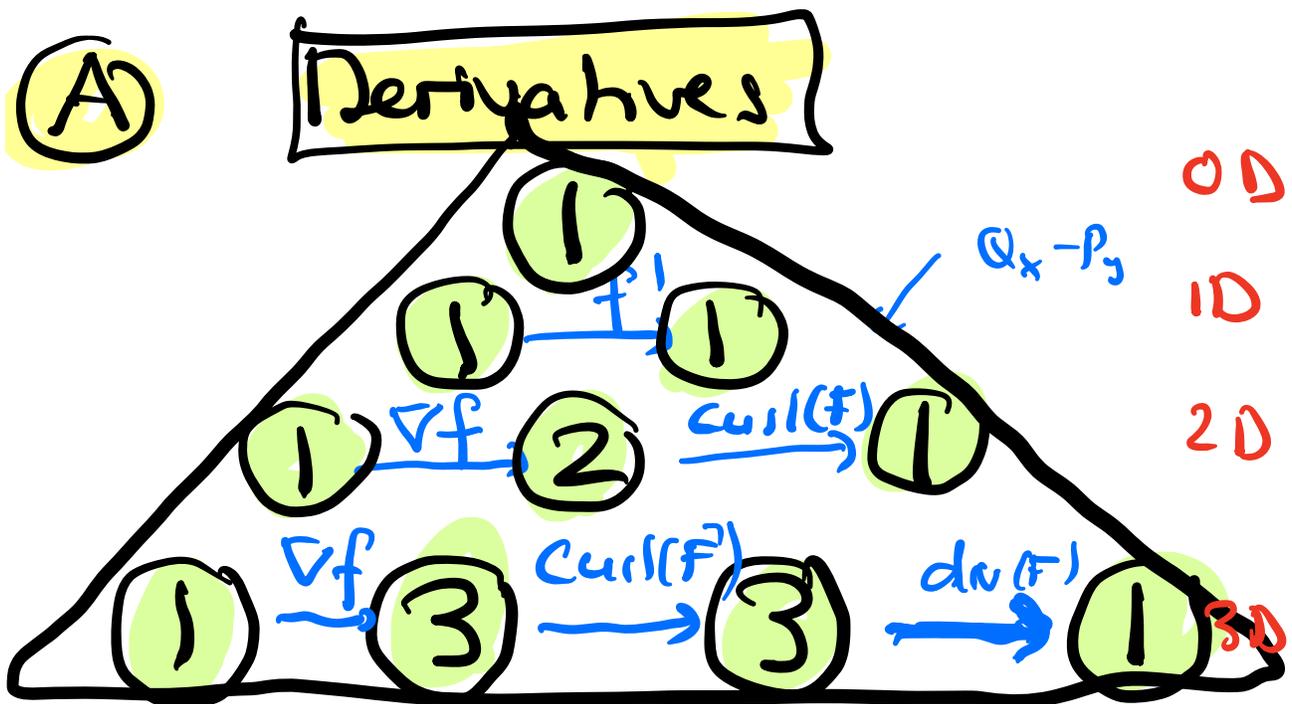
Volume $\sigma = \text{Mass}$

$$F(r) \cancel{4\pi r^2} = \cancel{4\pi} M$$

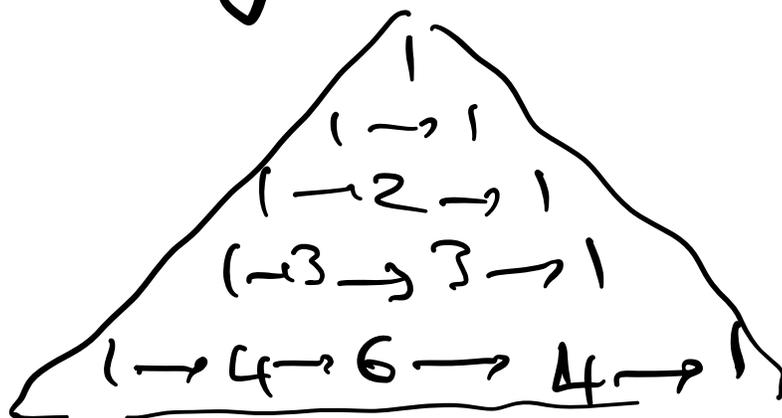
$$F(r) = \frac{M}{r^2}$$

Good old Newton's law of gravity.

3 diagrams



This actually continues
to any dimension



How to continue without
cross products? not in this
course
